

BREADTH FIRST SEARCH

BFS

Breadth-first search

- ▶ What is it good for?
- ▶ We have a graph and we want to visit every node → we can do it with BFS
- ▶ We visit every vertex exactly once
- ▶ We visit the neighbours then the neighbours of these new vertices and so on
- ▶ Memory complexity is not good: we have to store lots of references
- ▶ That's why DFS is usually preferred
- ▶ BUT it constructs a shortest path: Dijkstra algorithm does a BFS if all the edge weights are equal to 1

Breadth-first search

bfs(vertex)

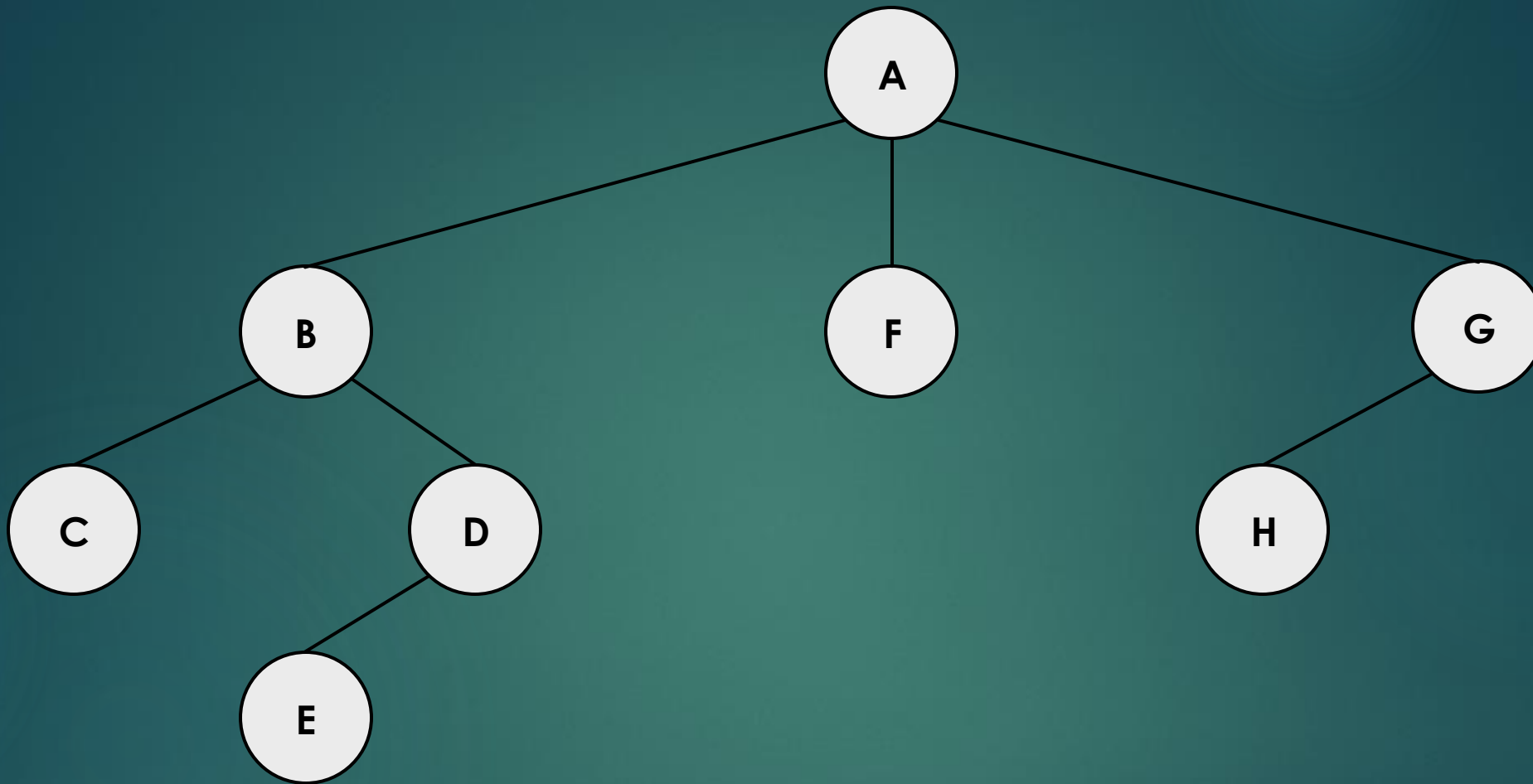
```
Queue queue  
vertex set visited true  
queue.enqueue(vertex)
```

```
while queue not empty  
    actual = queue.dequeue()
```

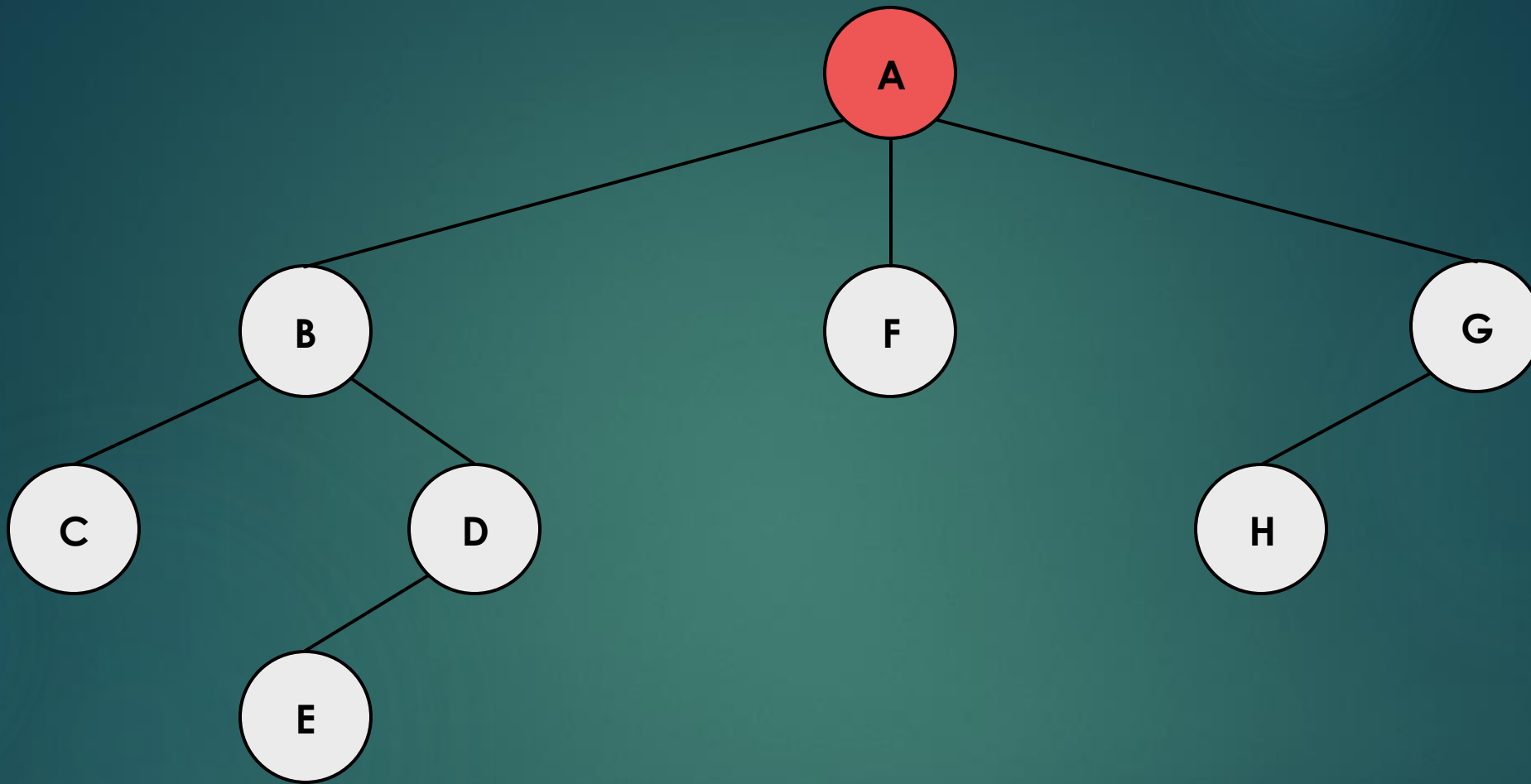
```
    for v in actual neighbours  
        if v is not visited  
            v set visited true  
            queue.enqueue(v)
```

We have an empty queue at the beginning
and we keep checking whether we have visited
the given node or not
~ keep iterating until queue is not empty

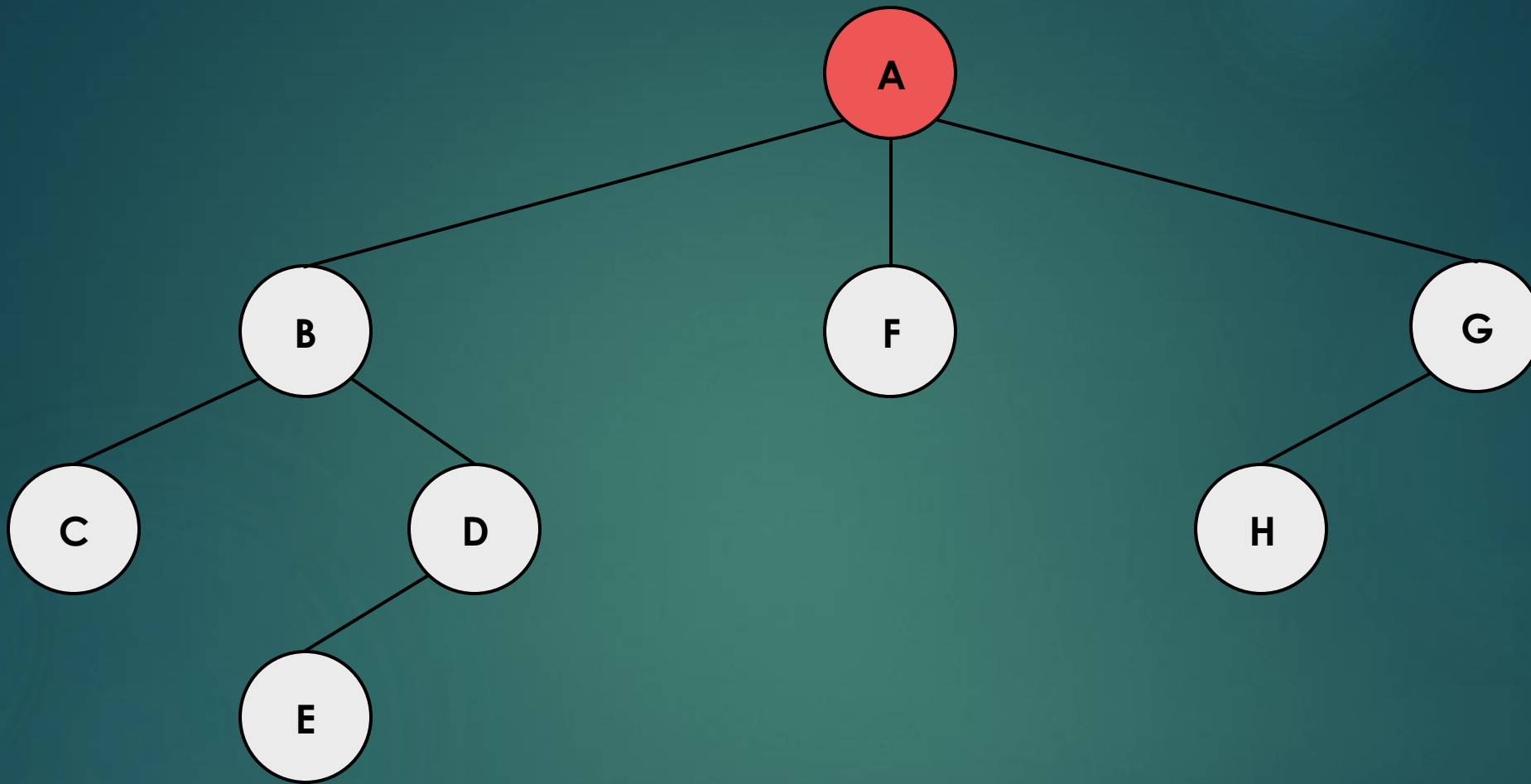
ITERATION



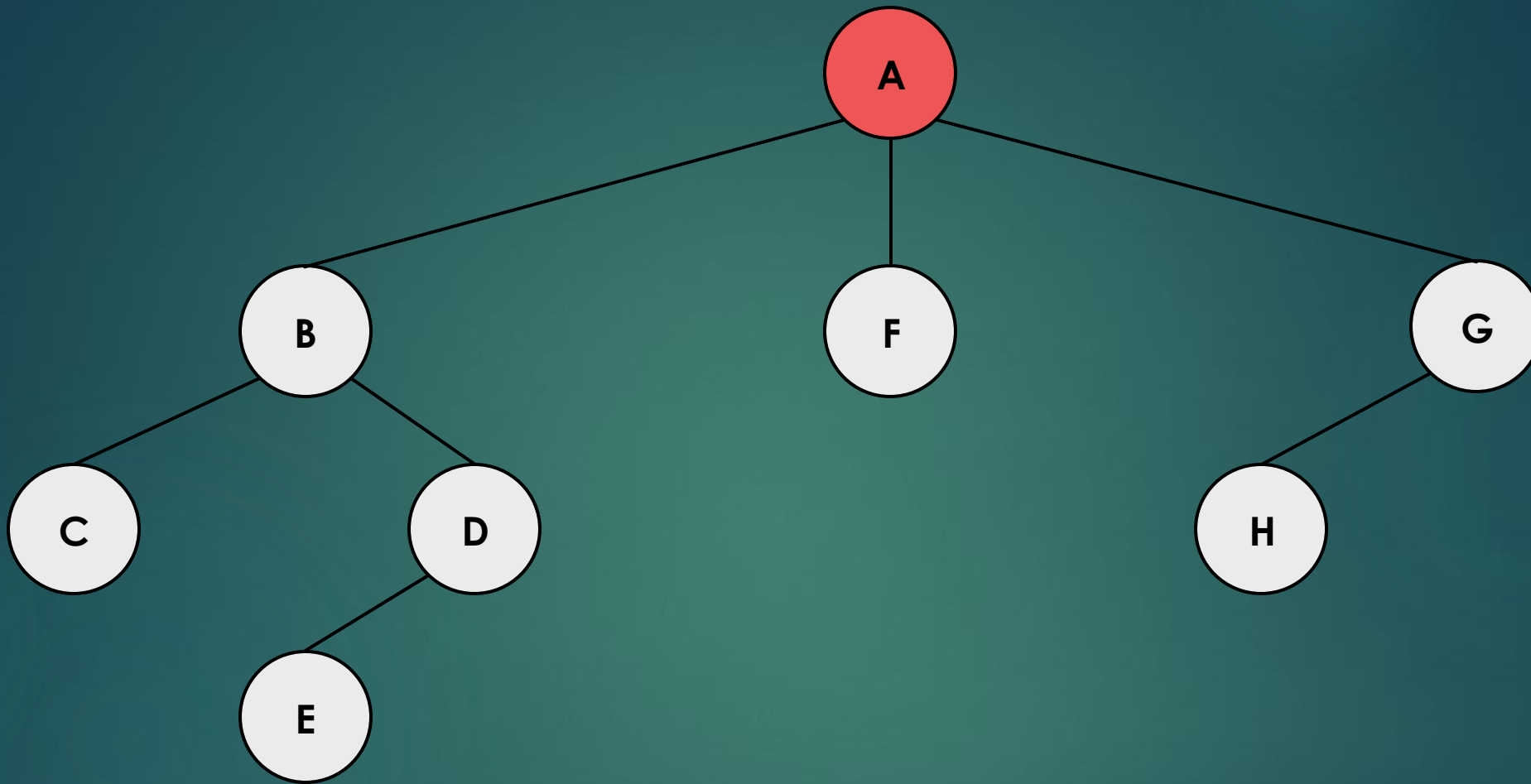
Queue: { }



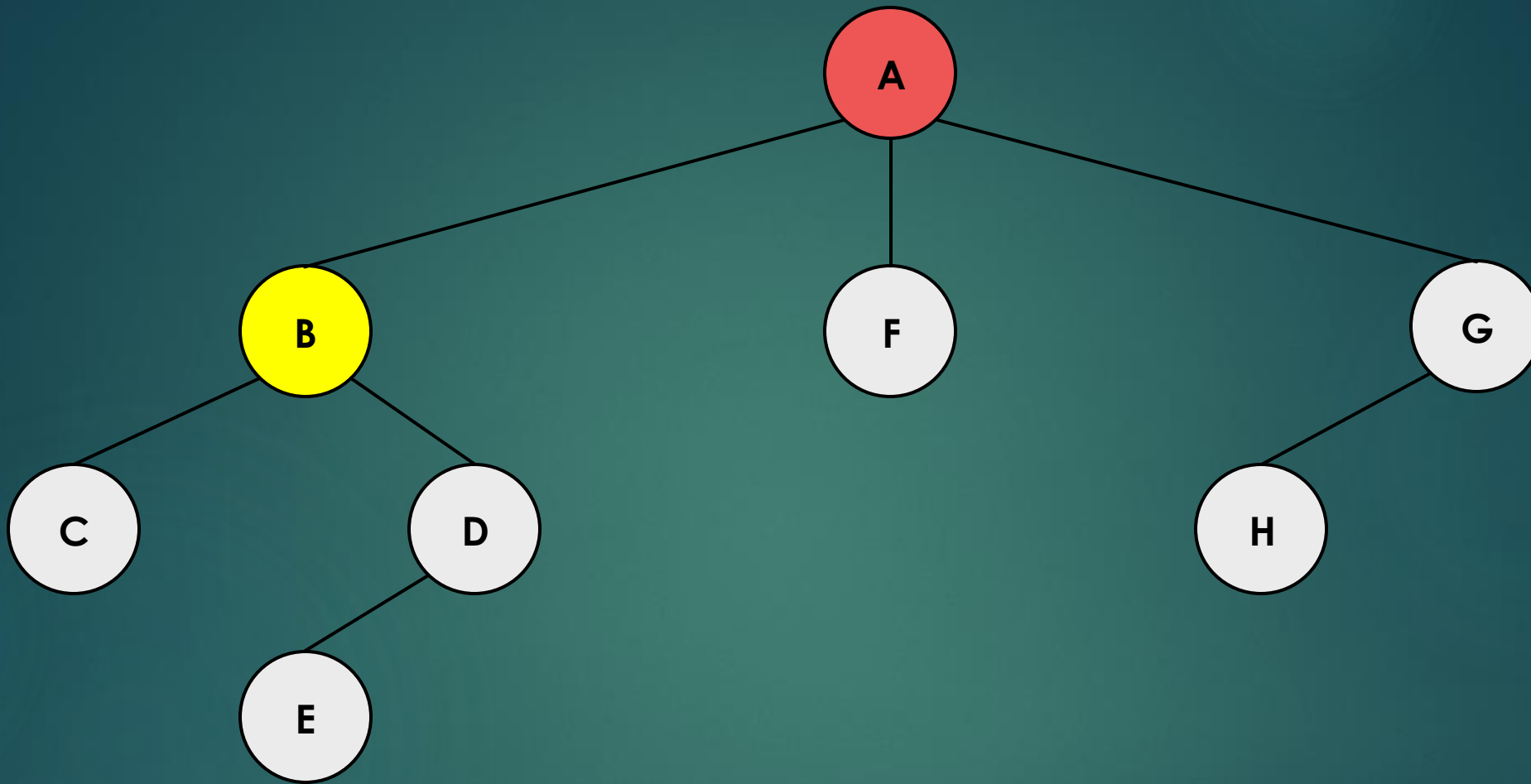
Queue: { A }



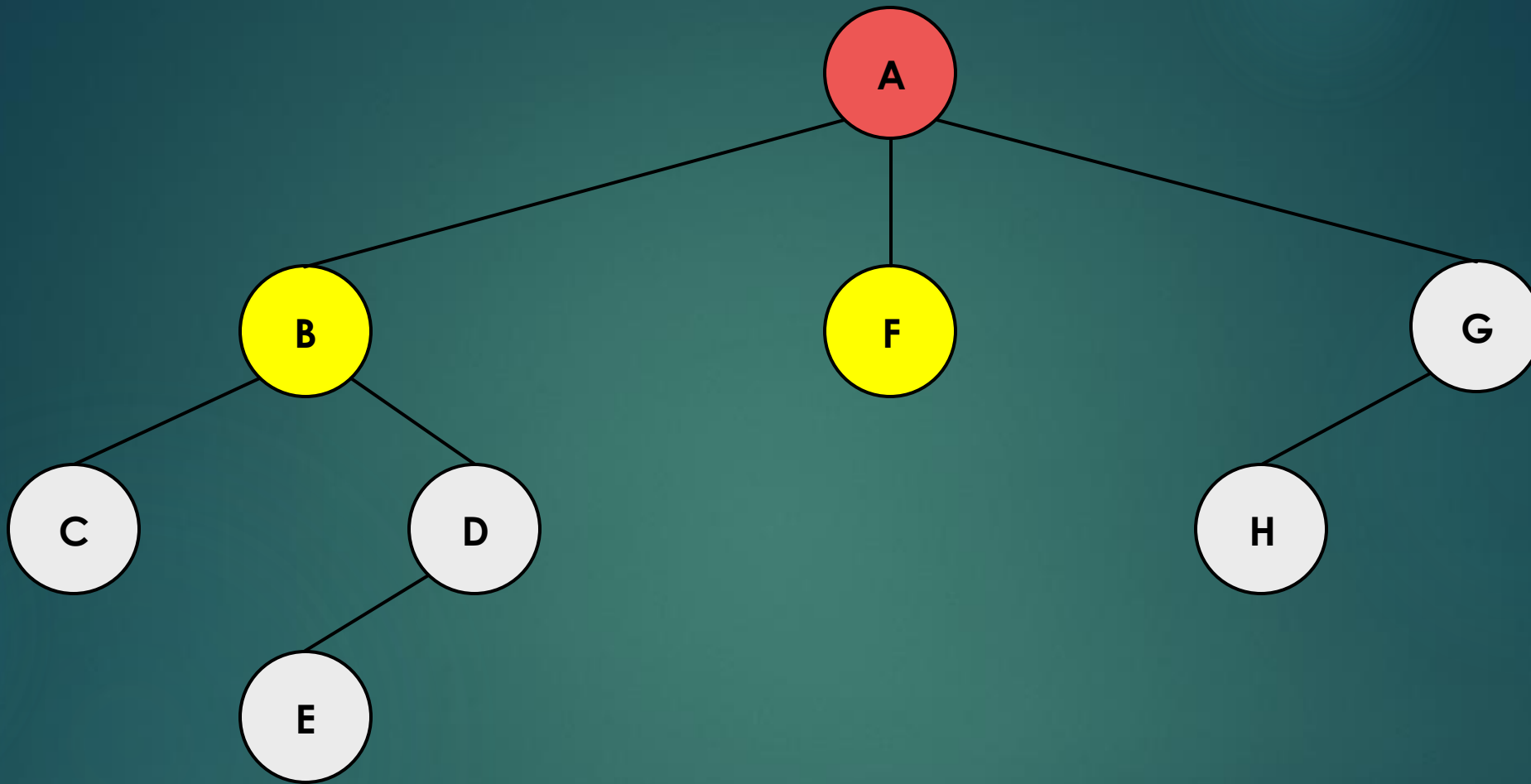
Queue: { **A** } dequeue node A to be able to process its



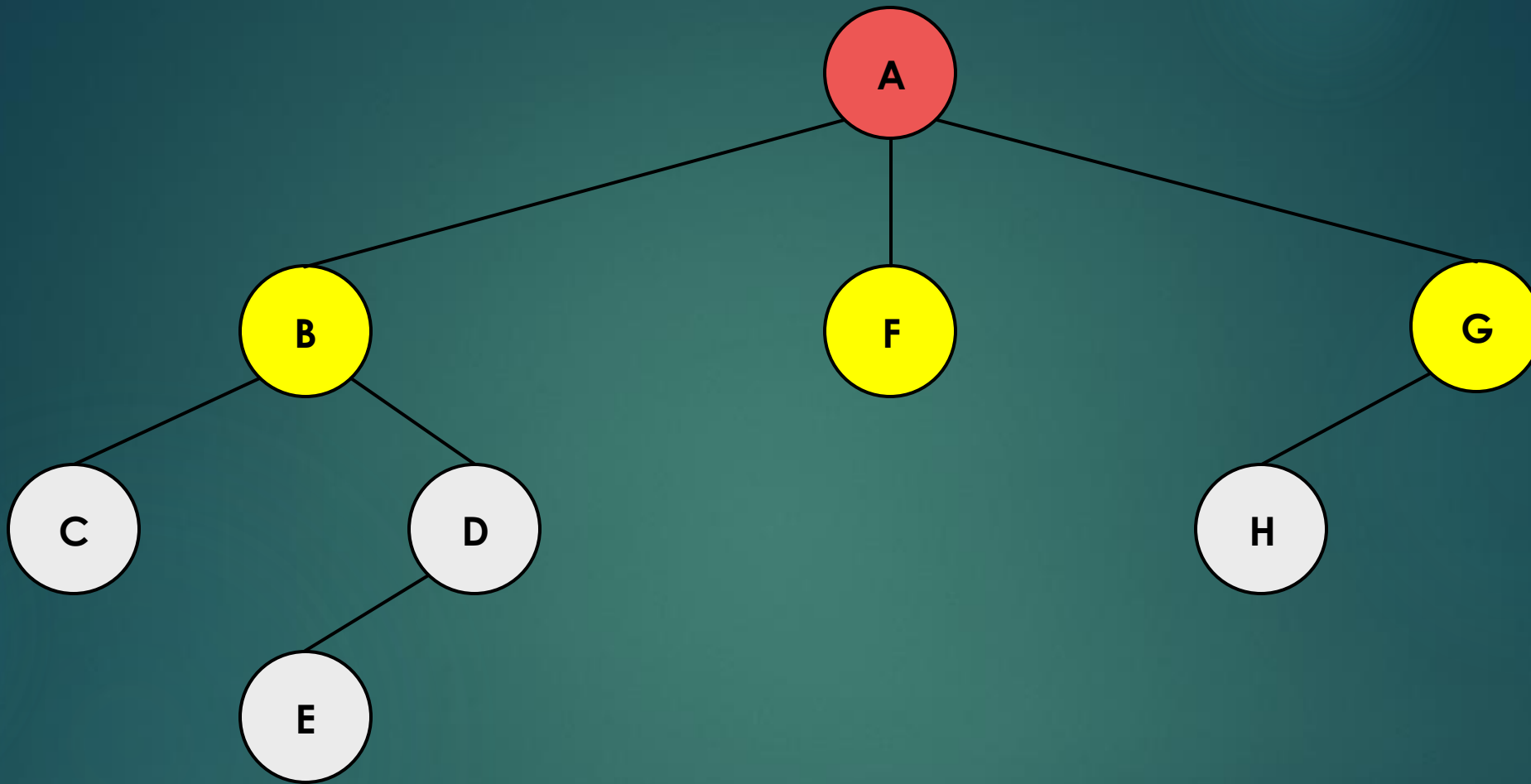
Queue: { } dequeue node A to be able to process its neighbours → visit all the children, if a node is unvisited then enqueue it !!!



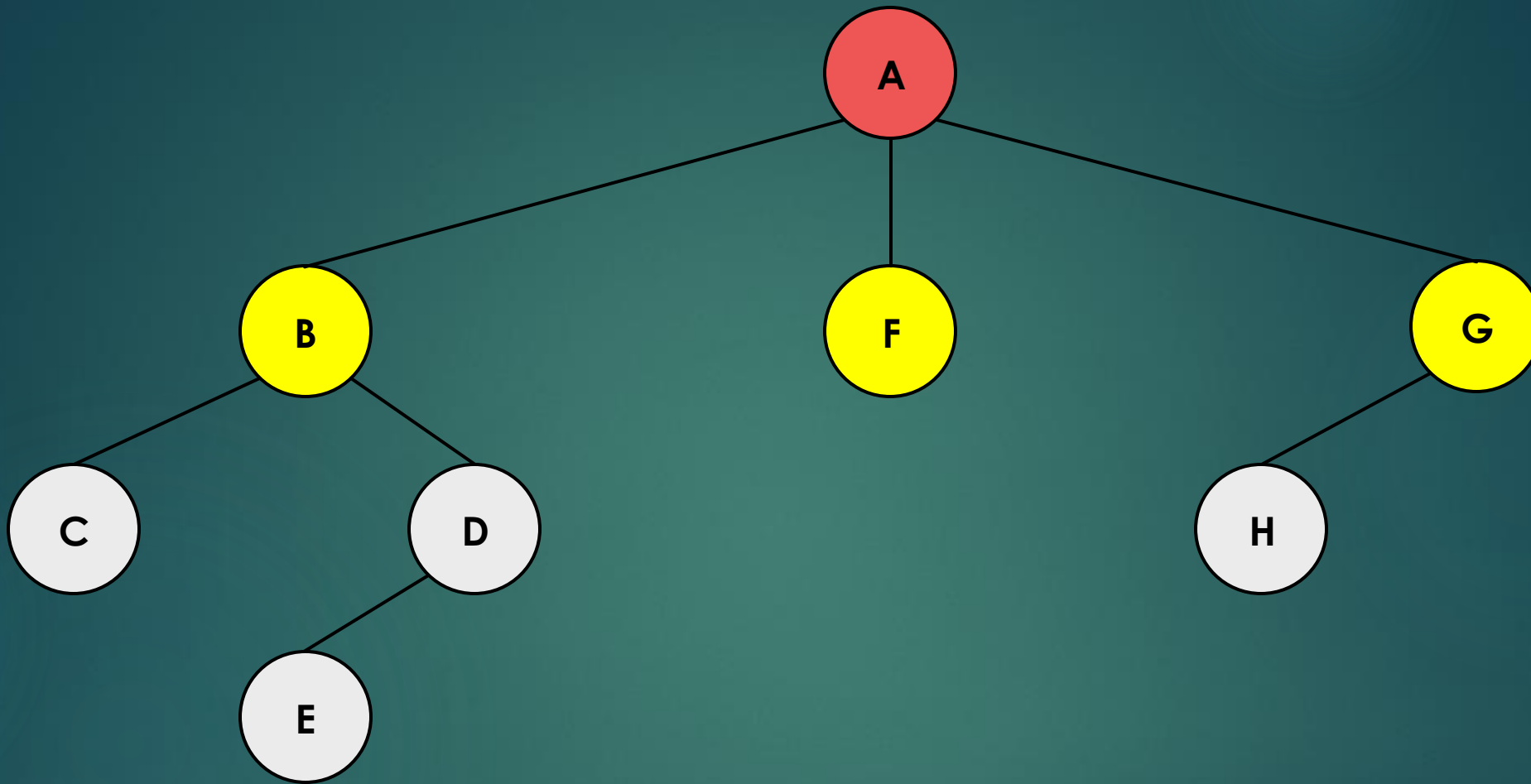
Queue: { B } node B is not visited → put it to the queue



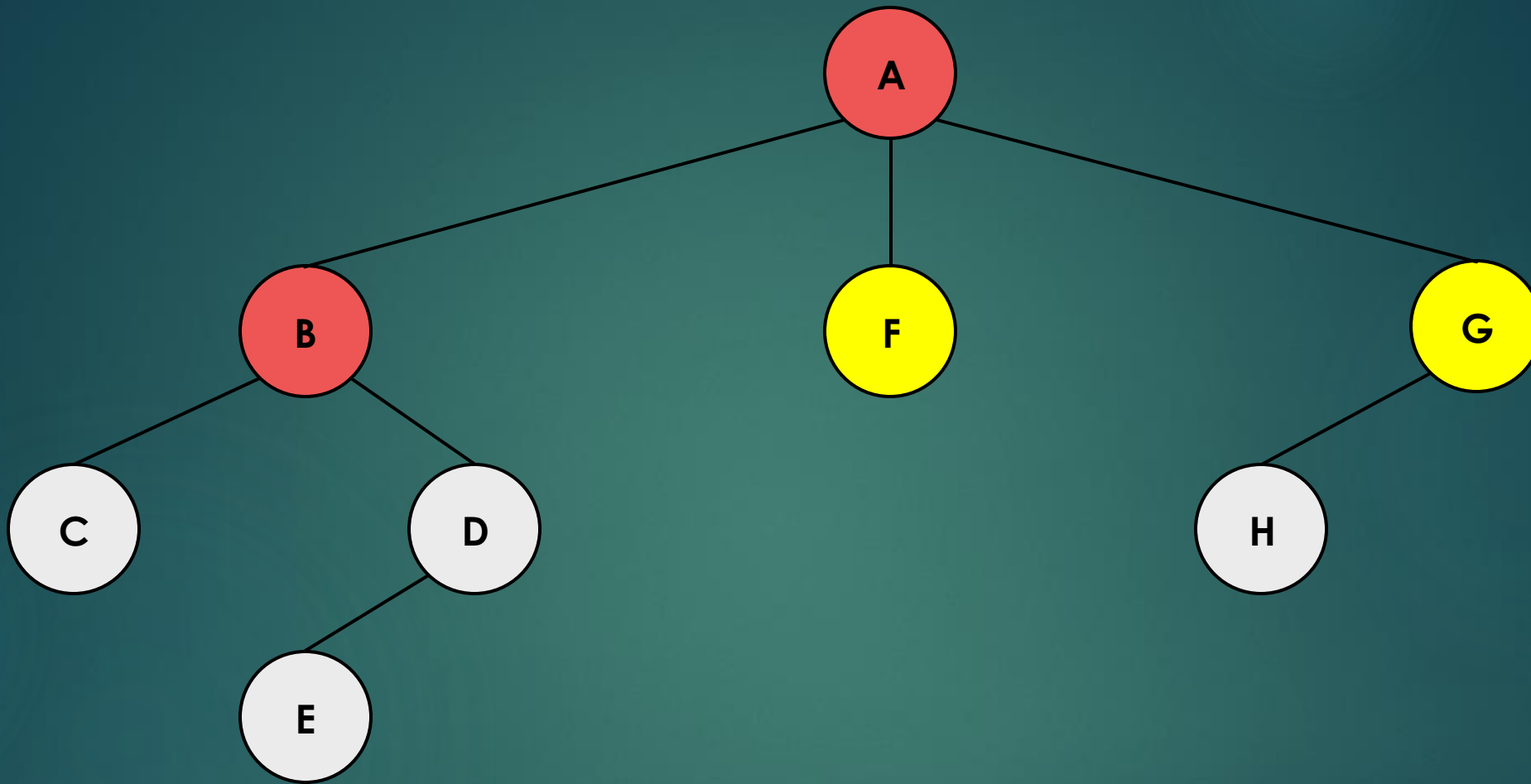
Queue: { F B } node F is not visited → put it to the queue



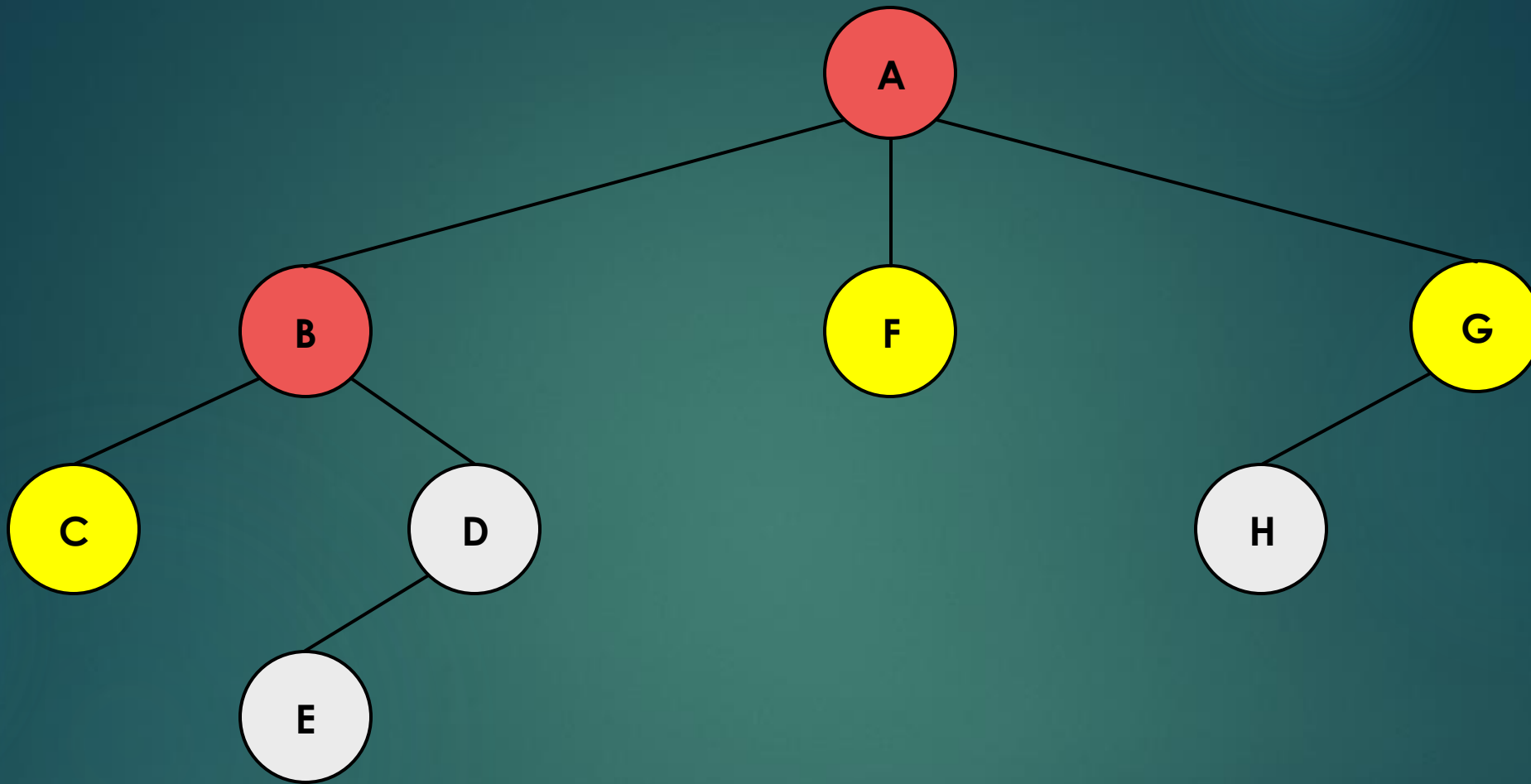
Queue: { G F B } node G is not visited → put it to the queue



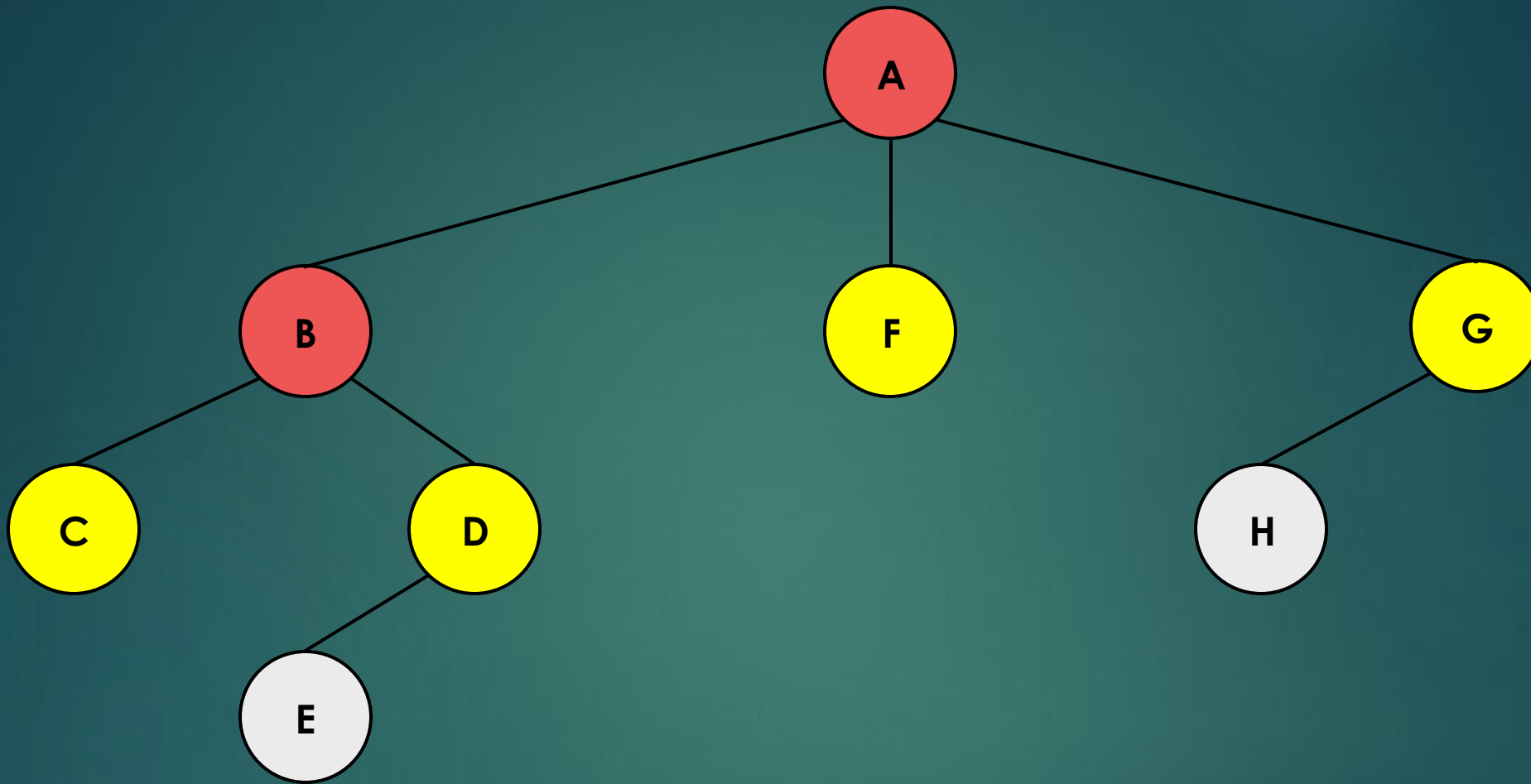
Queue: { G F **B** } dequeue the next node → it is B and visit its children + put them into the queue if necessary



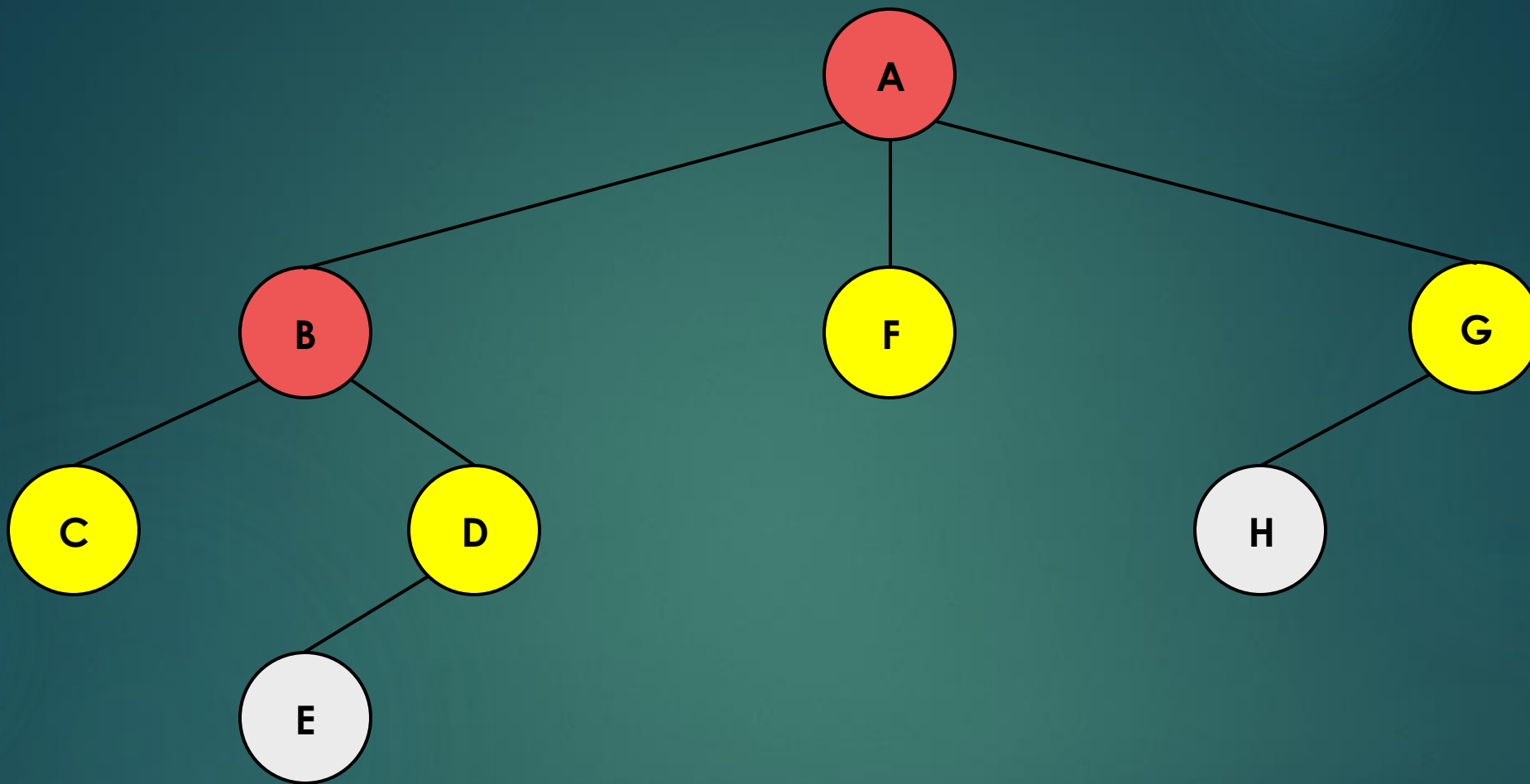
Queue: { G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary



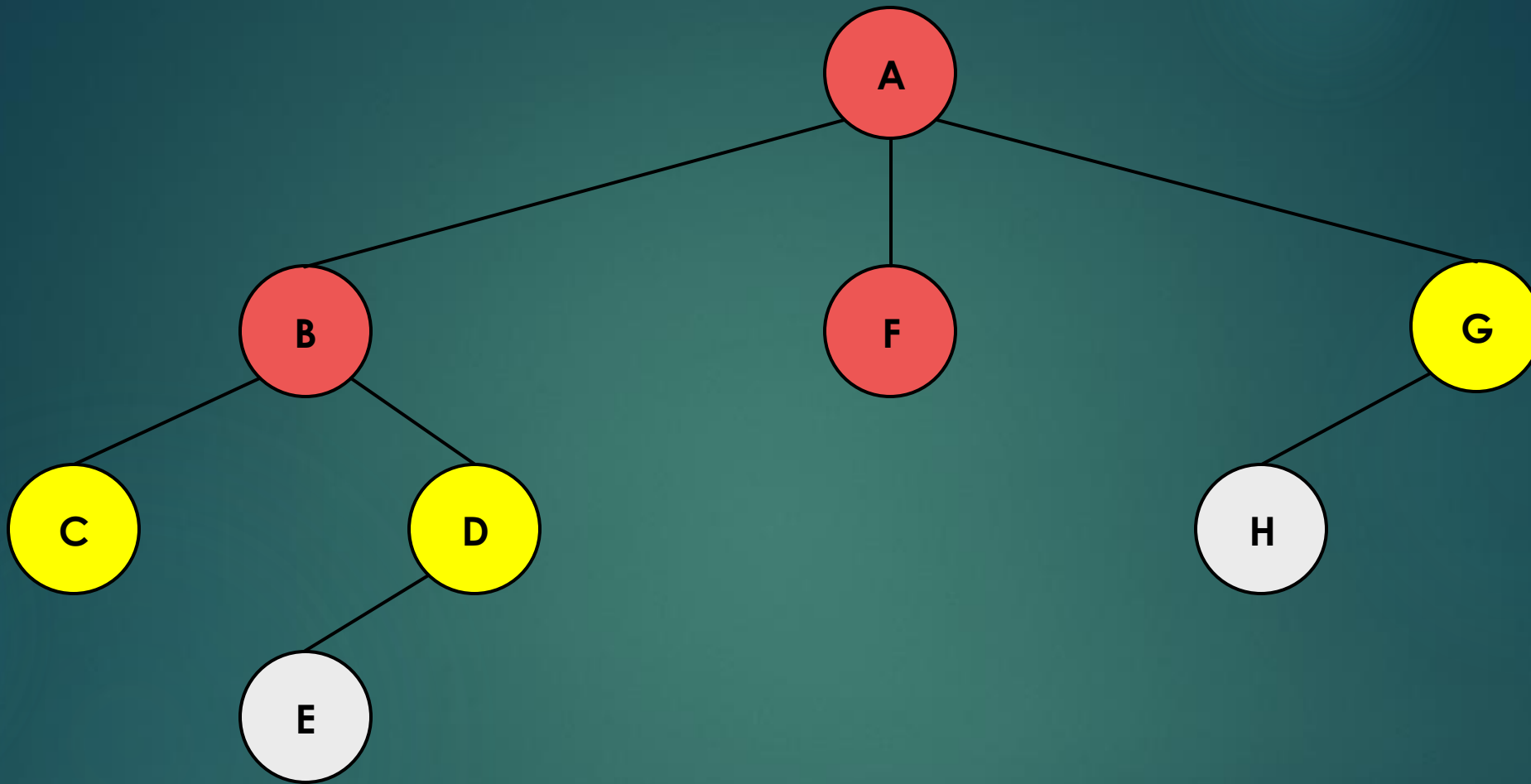
Queue: { C G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary



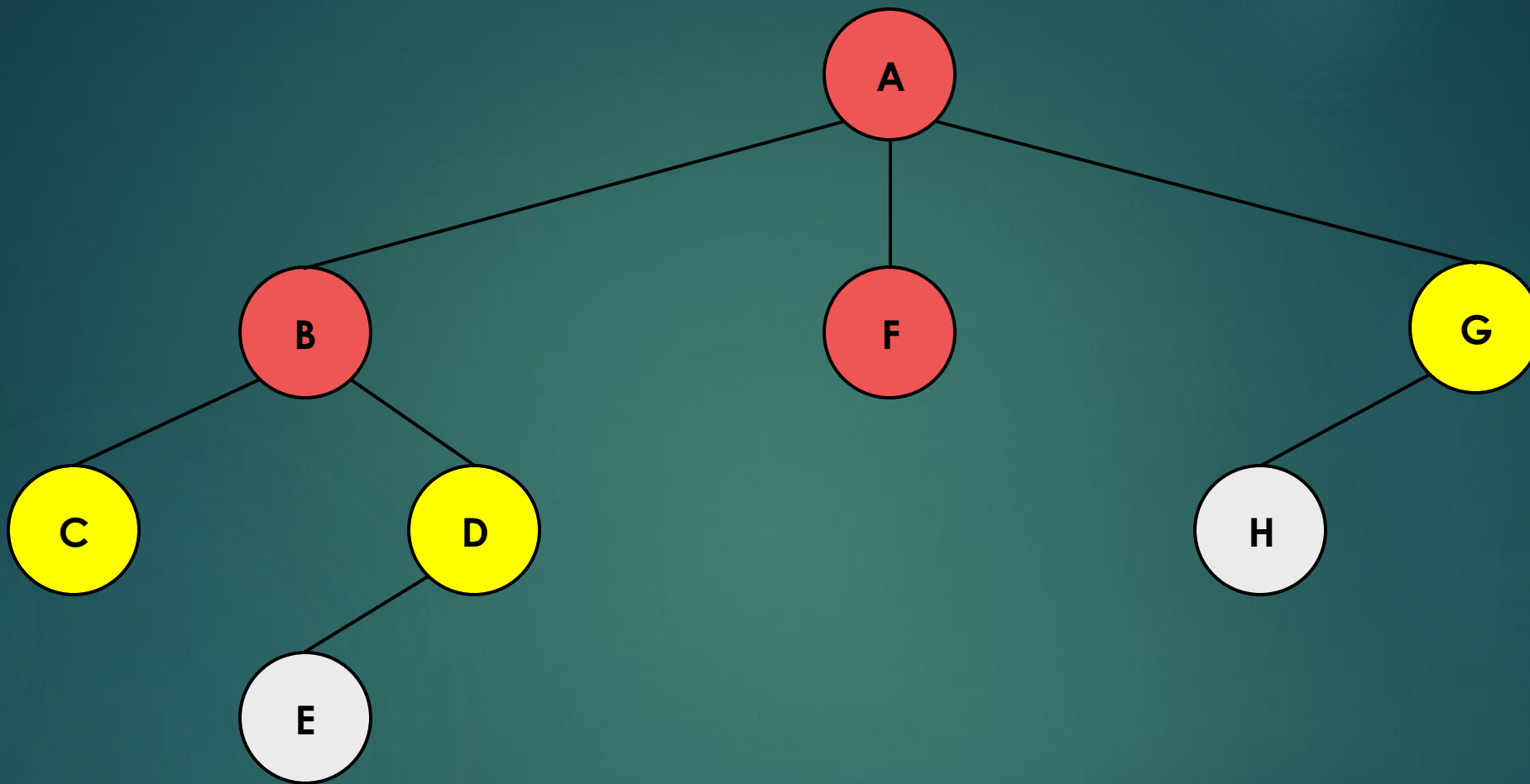
Queue: { D C G F } dequeue the next node → it is G and visit its children + put them into the queue if necessary



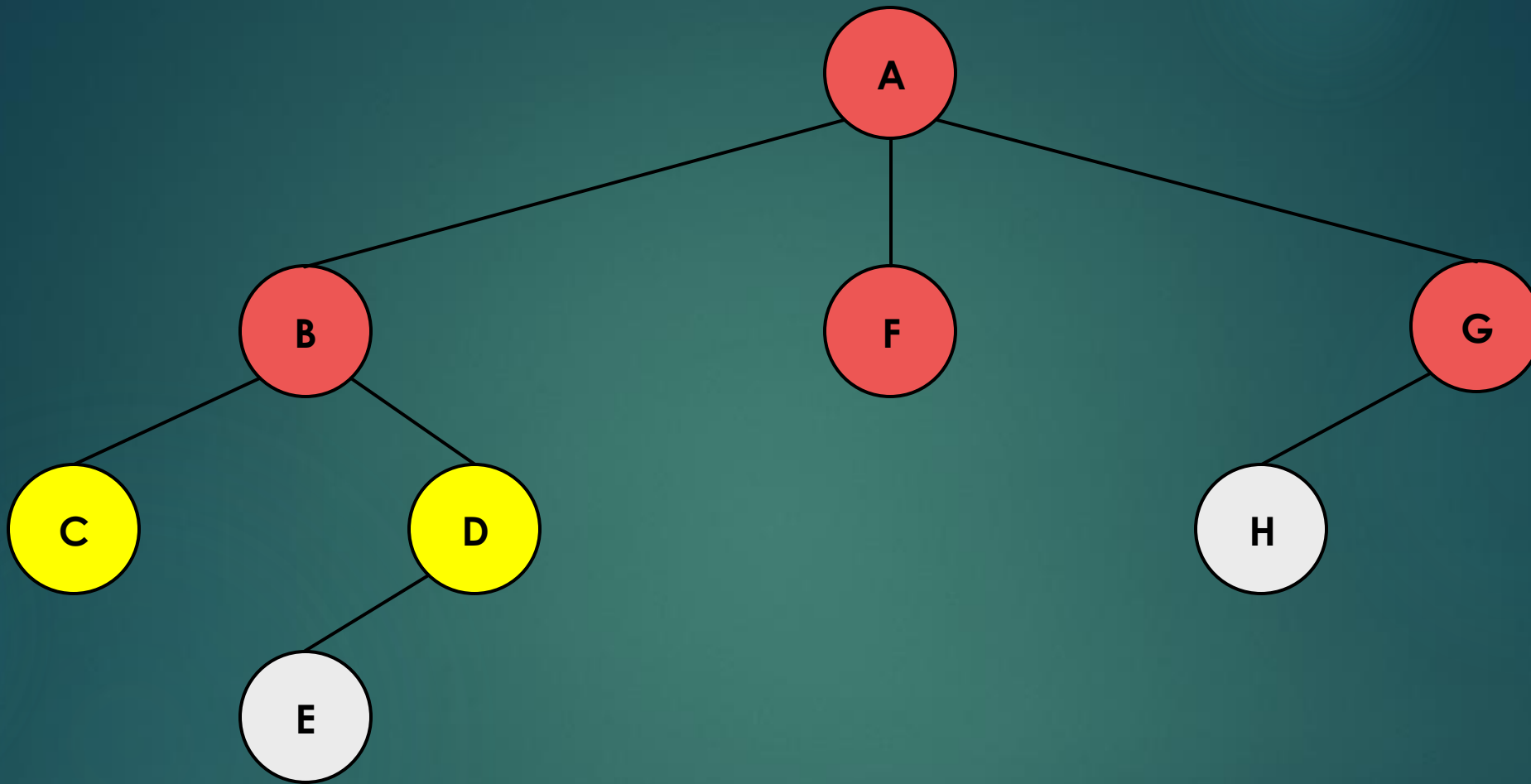
Queue: { D C G **F** }



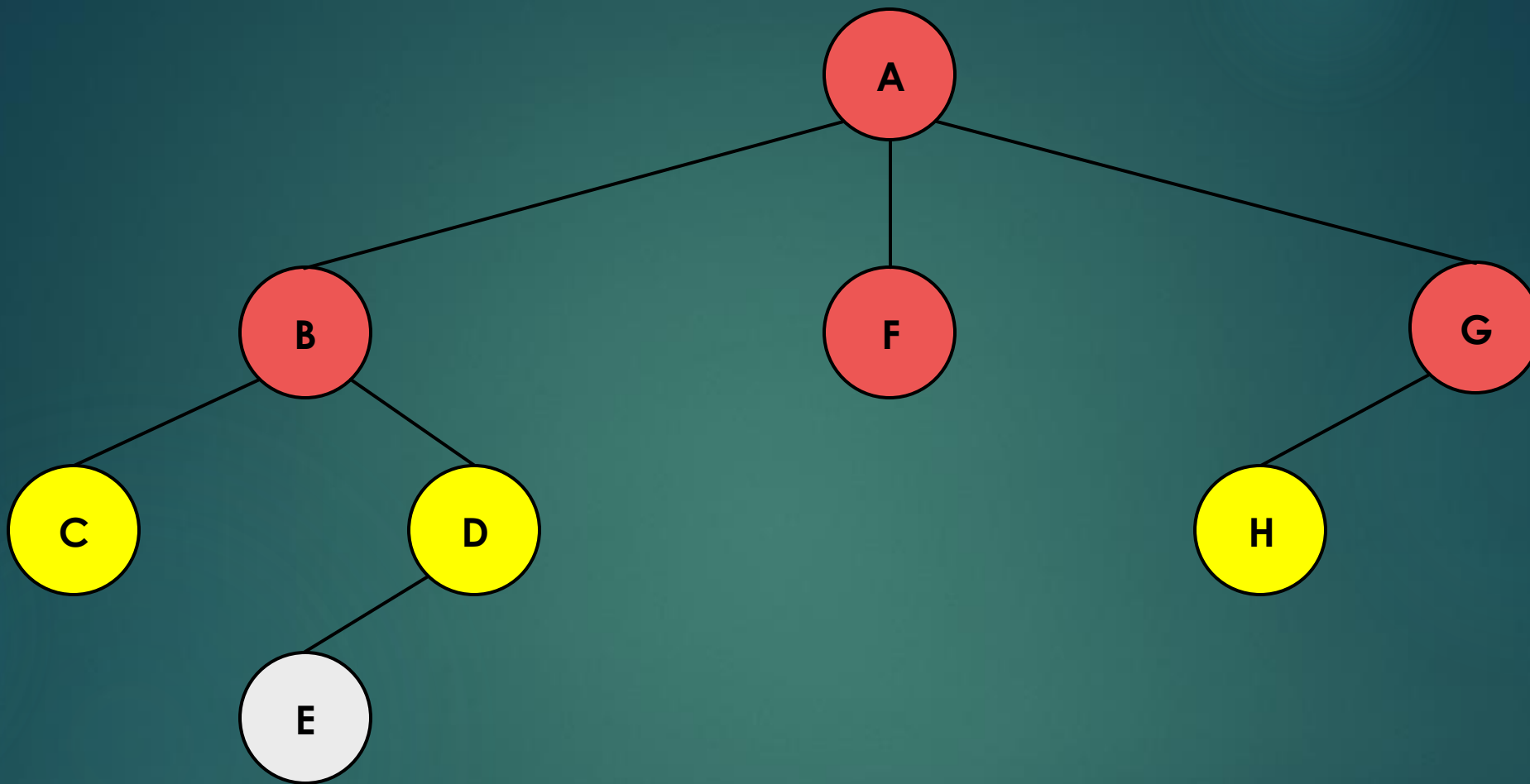
Queue: { D C G }



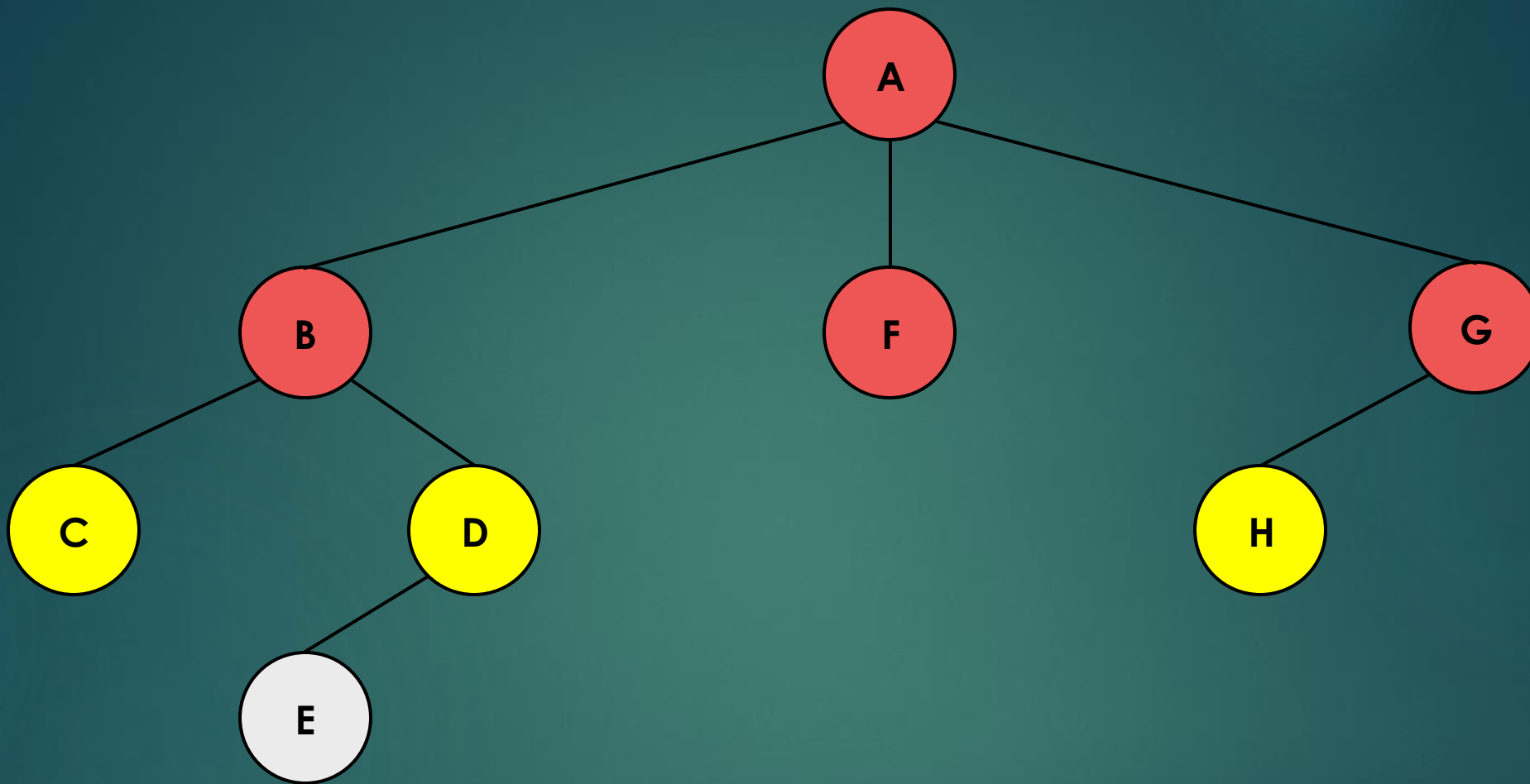
Queue: { D C **G** }



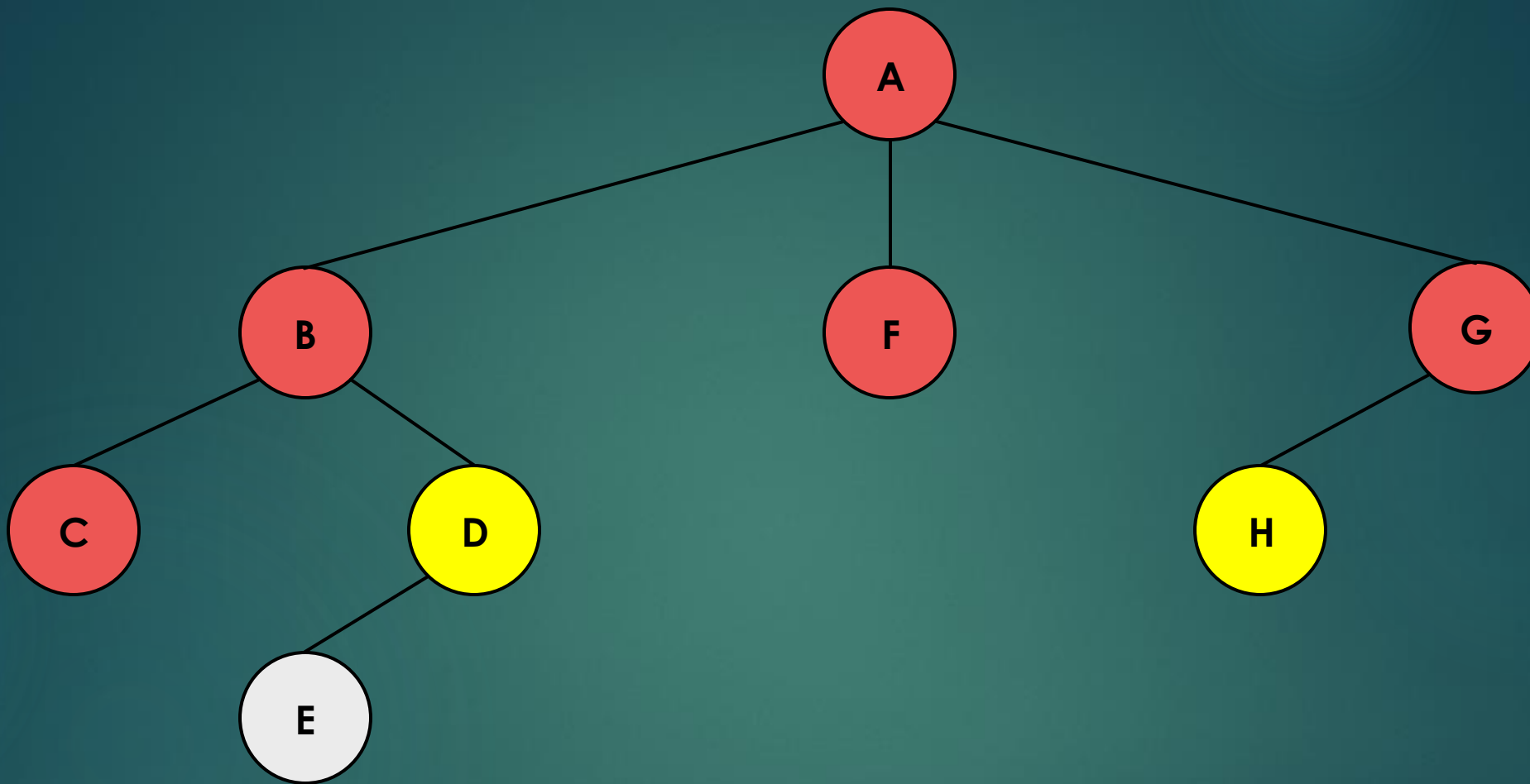
Queue: { D C }



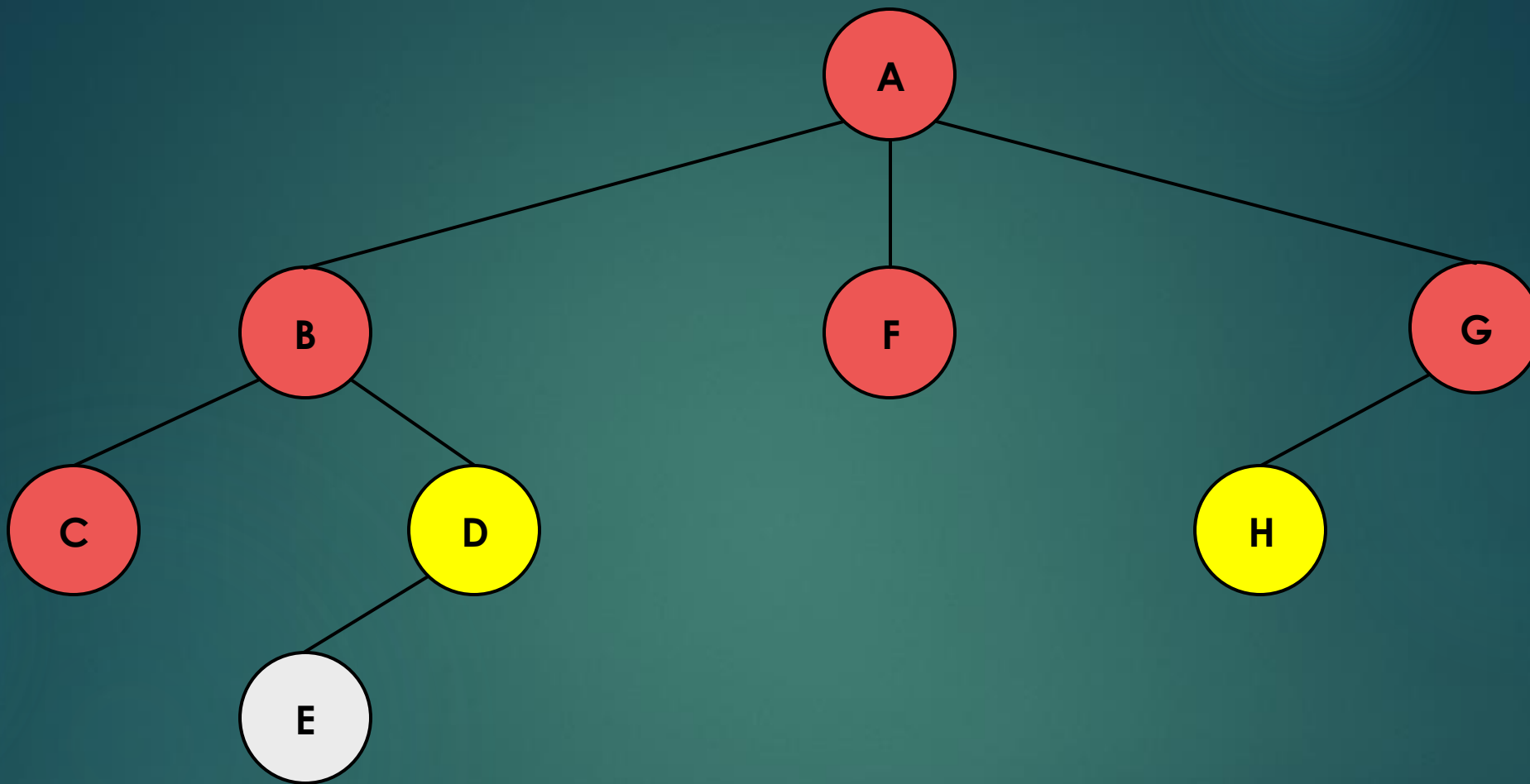
Queue: { H D C }



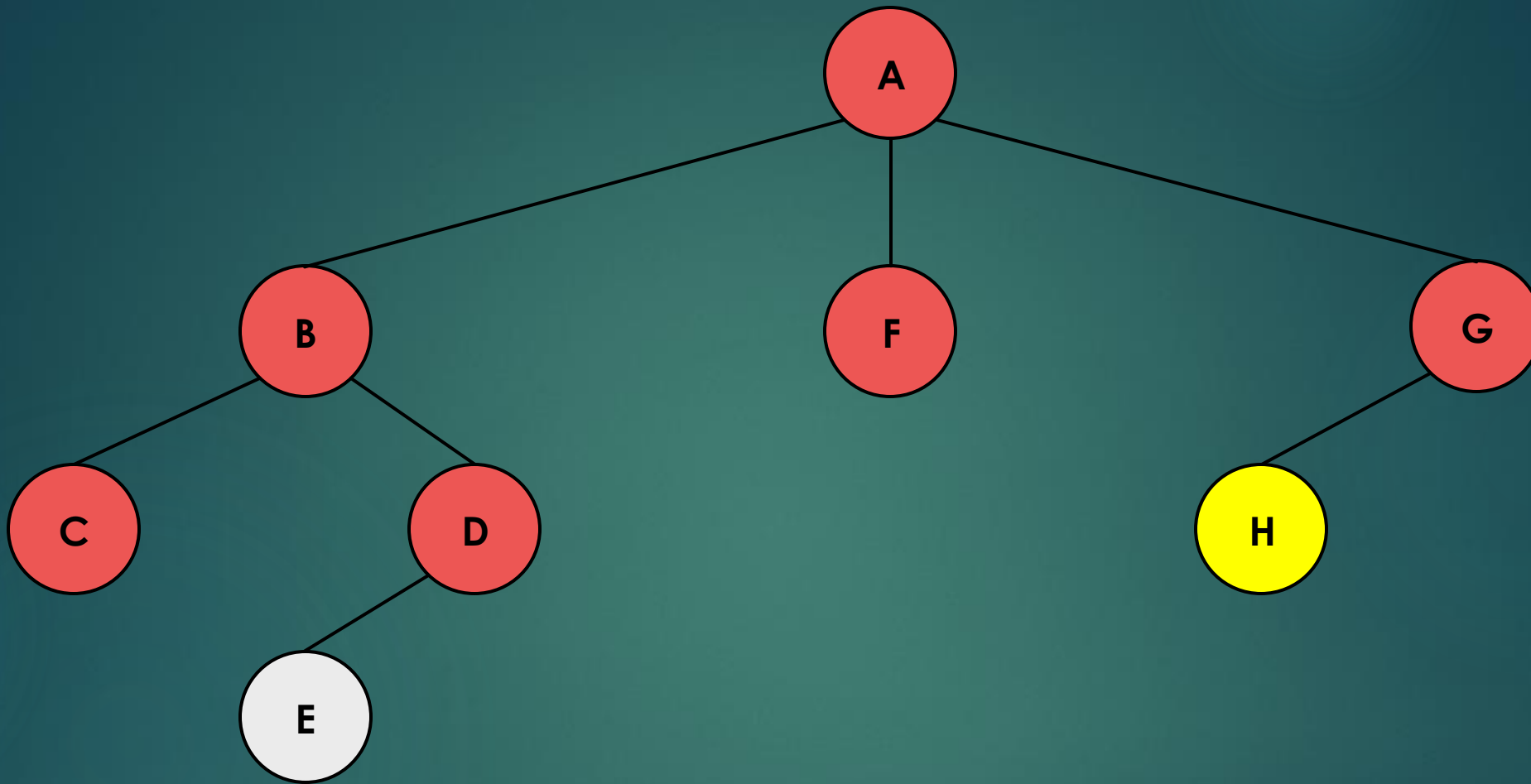
Queue: { H D **C** }



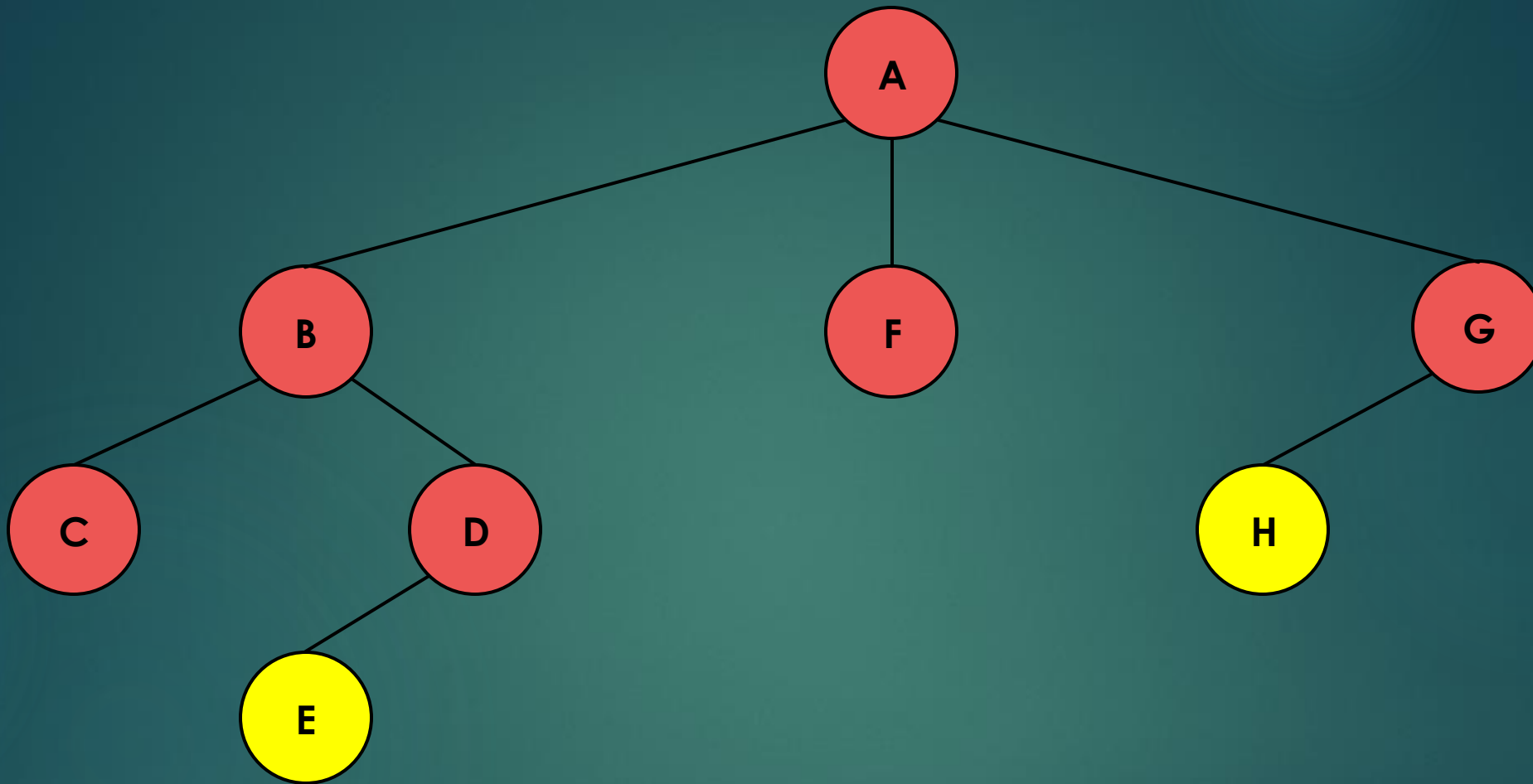
Queue: { H D }



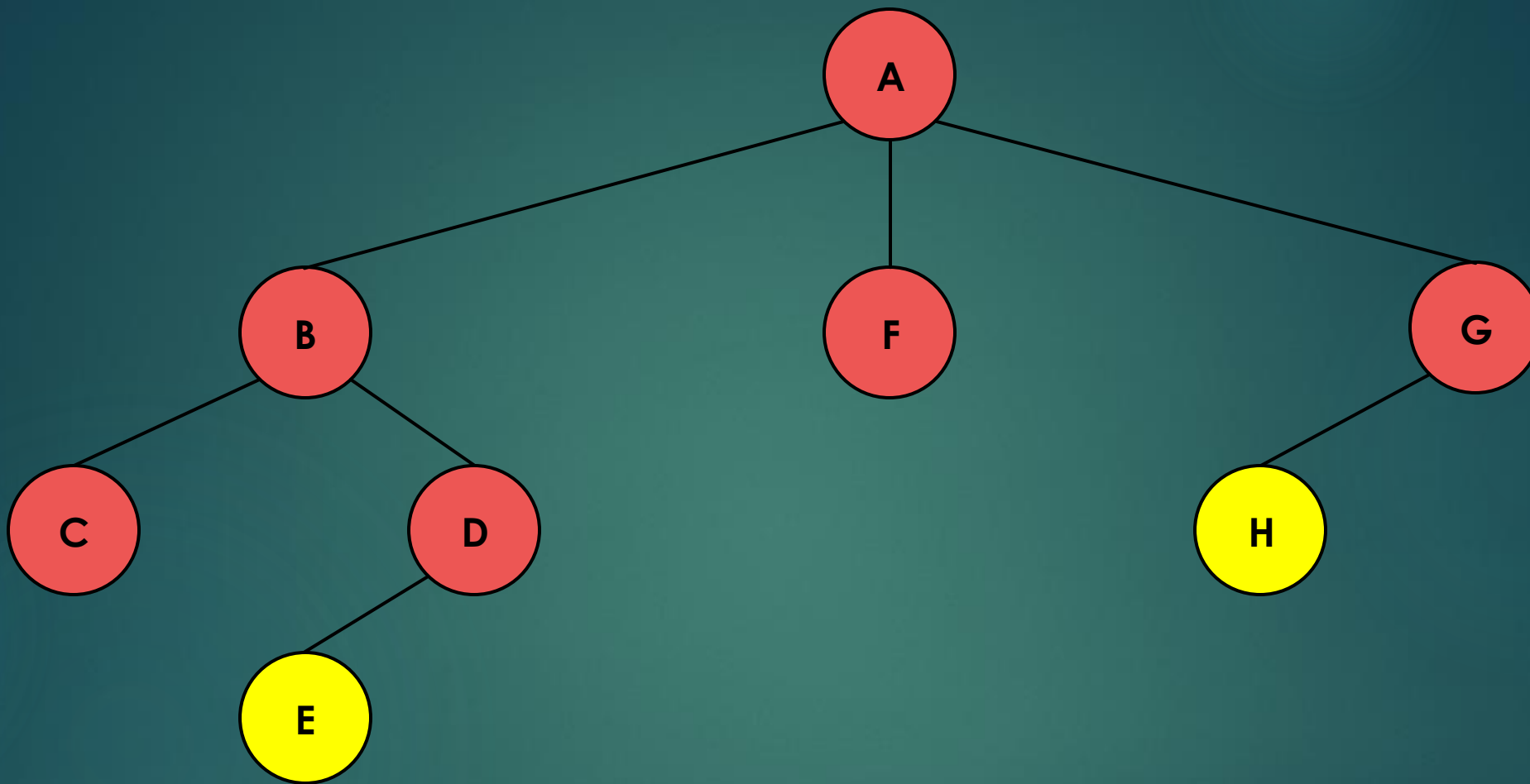
Queue: { H **D** }



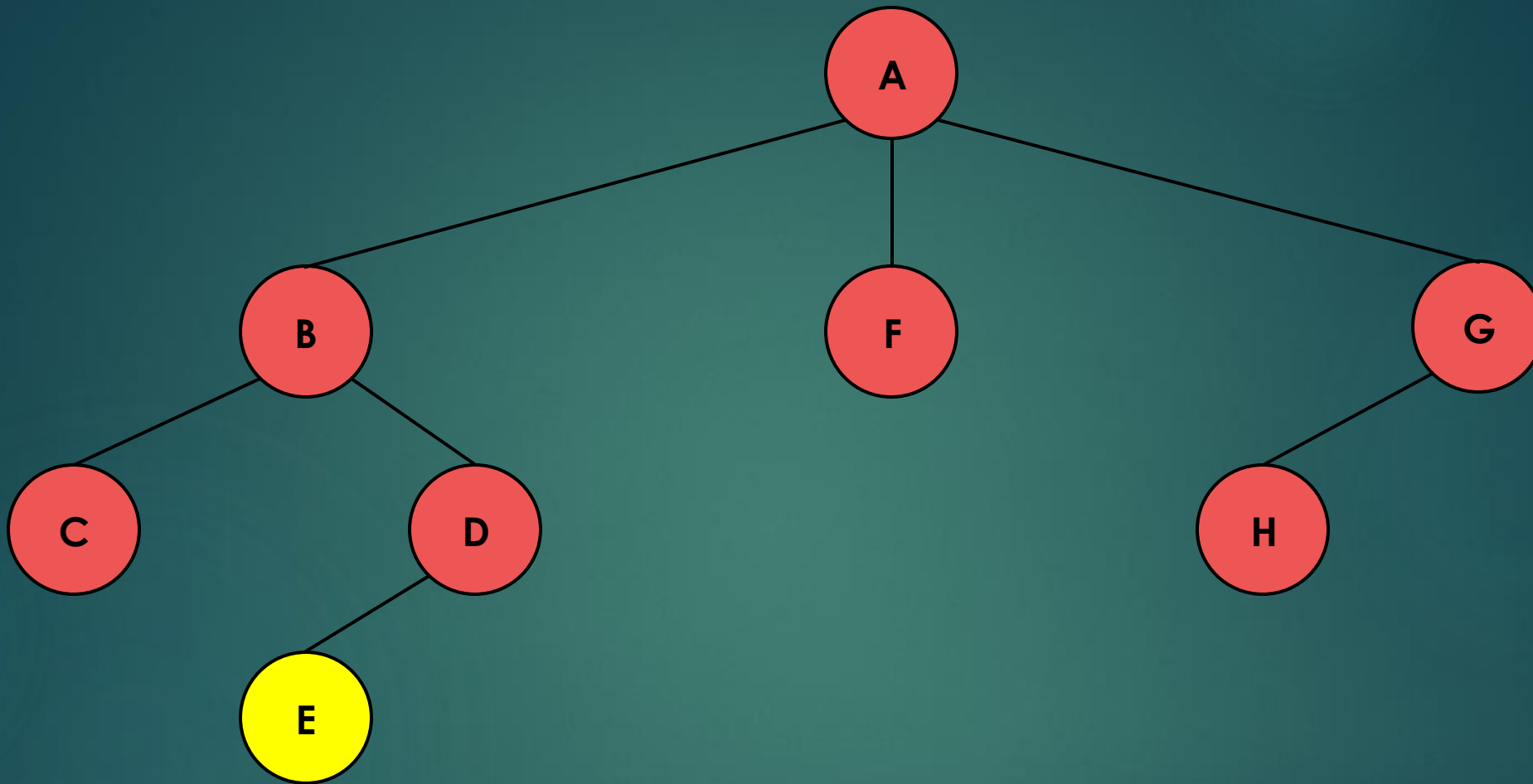
Queue: { H }



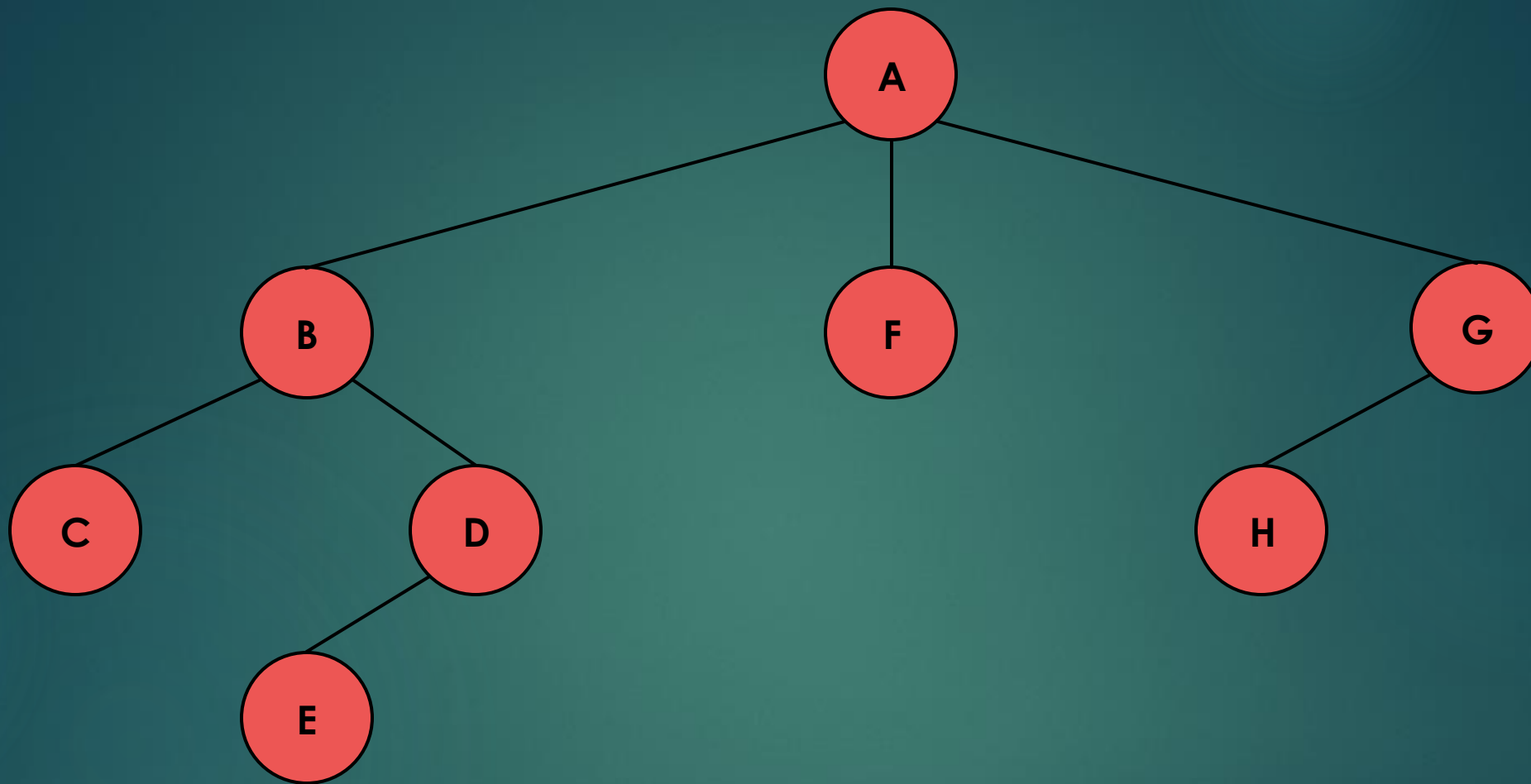
Queue: { E H }



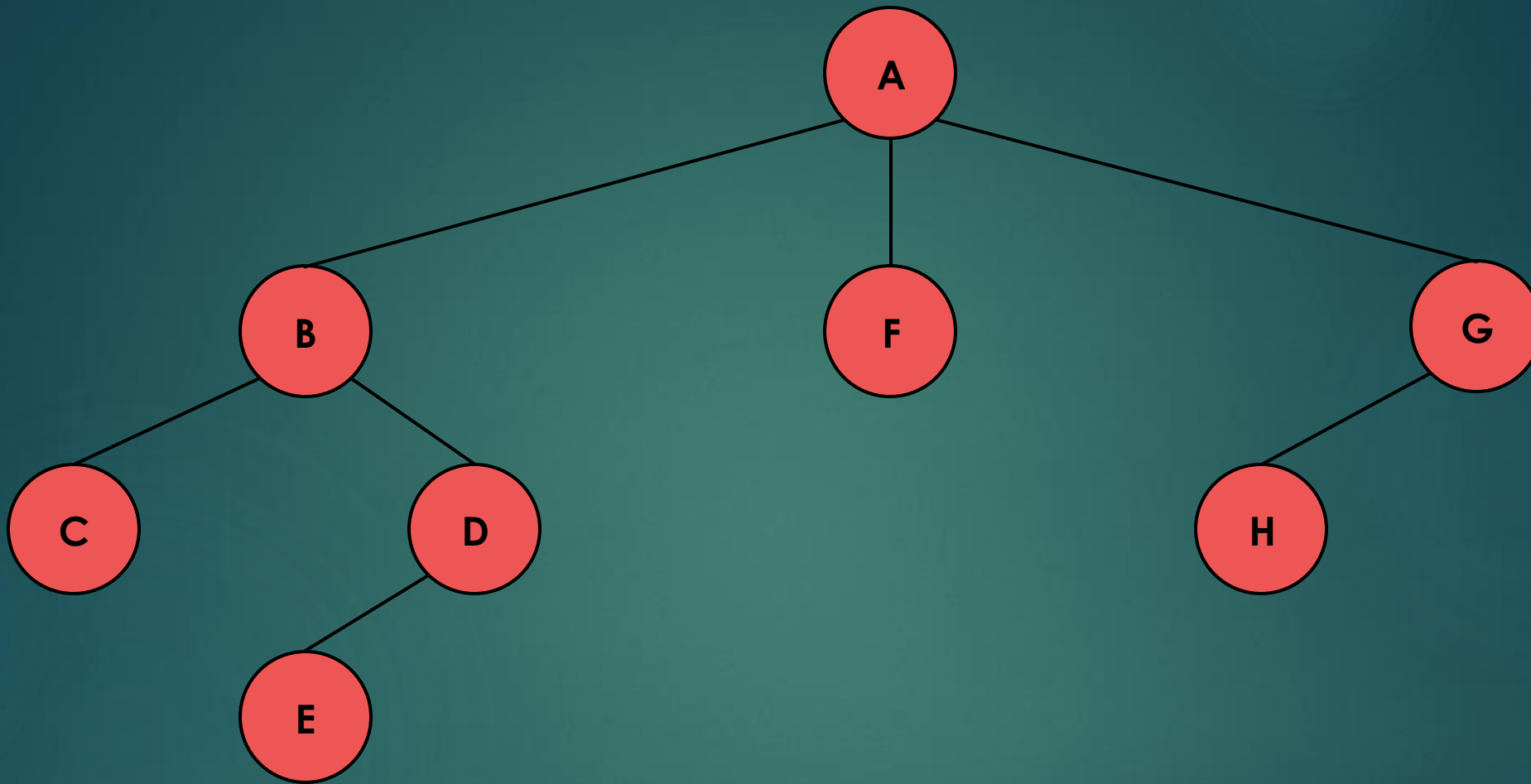
Queue: { E **H** }



Queue: { E }

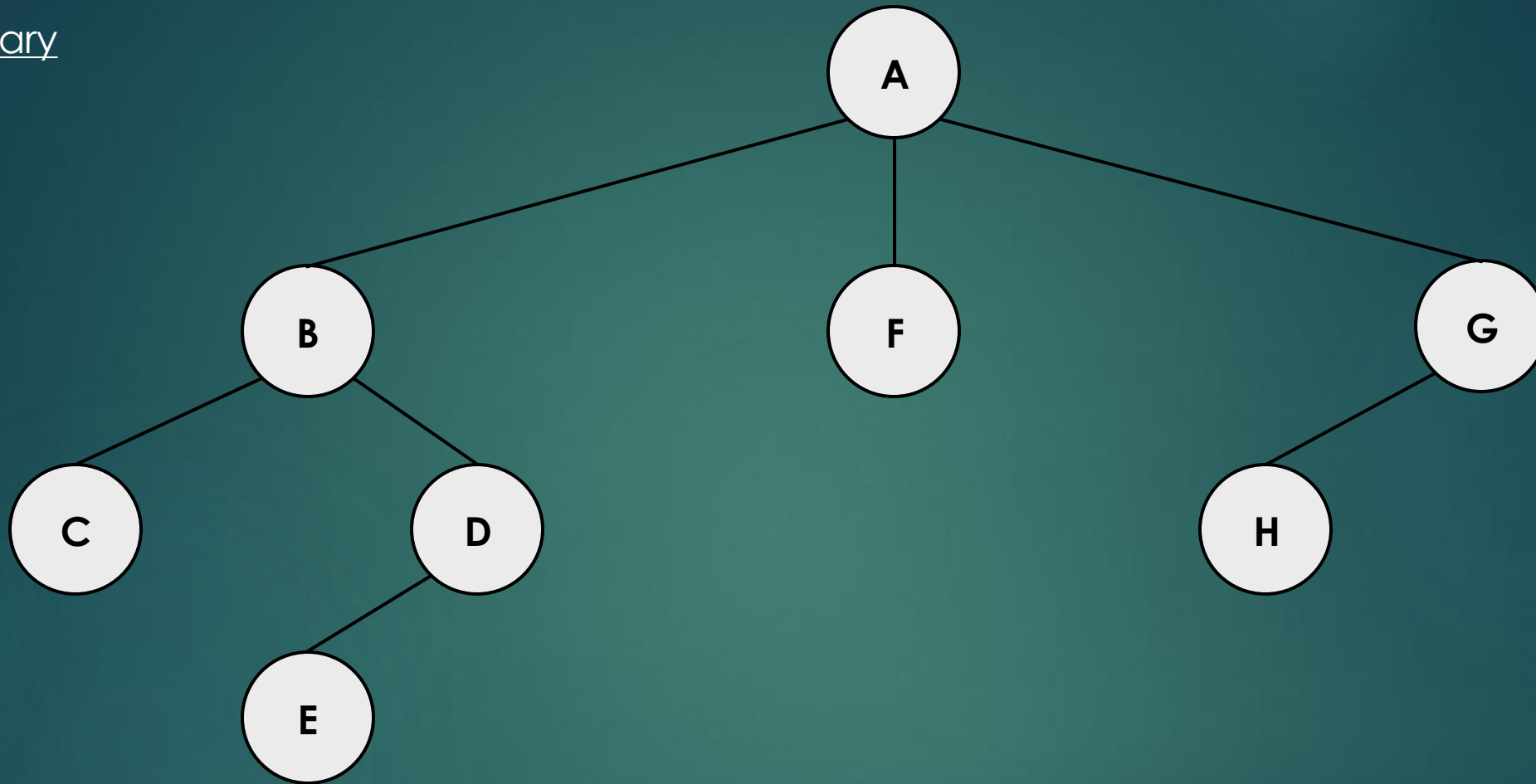


Queue: { **E** }

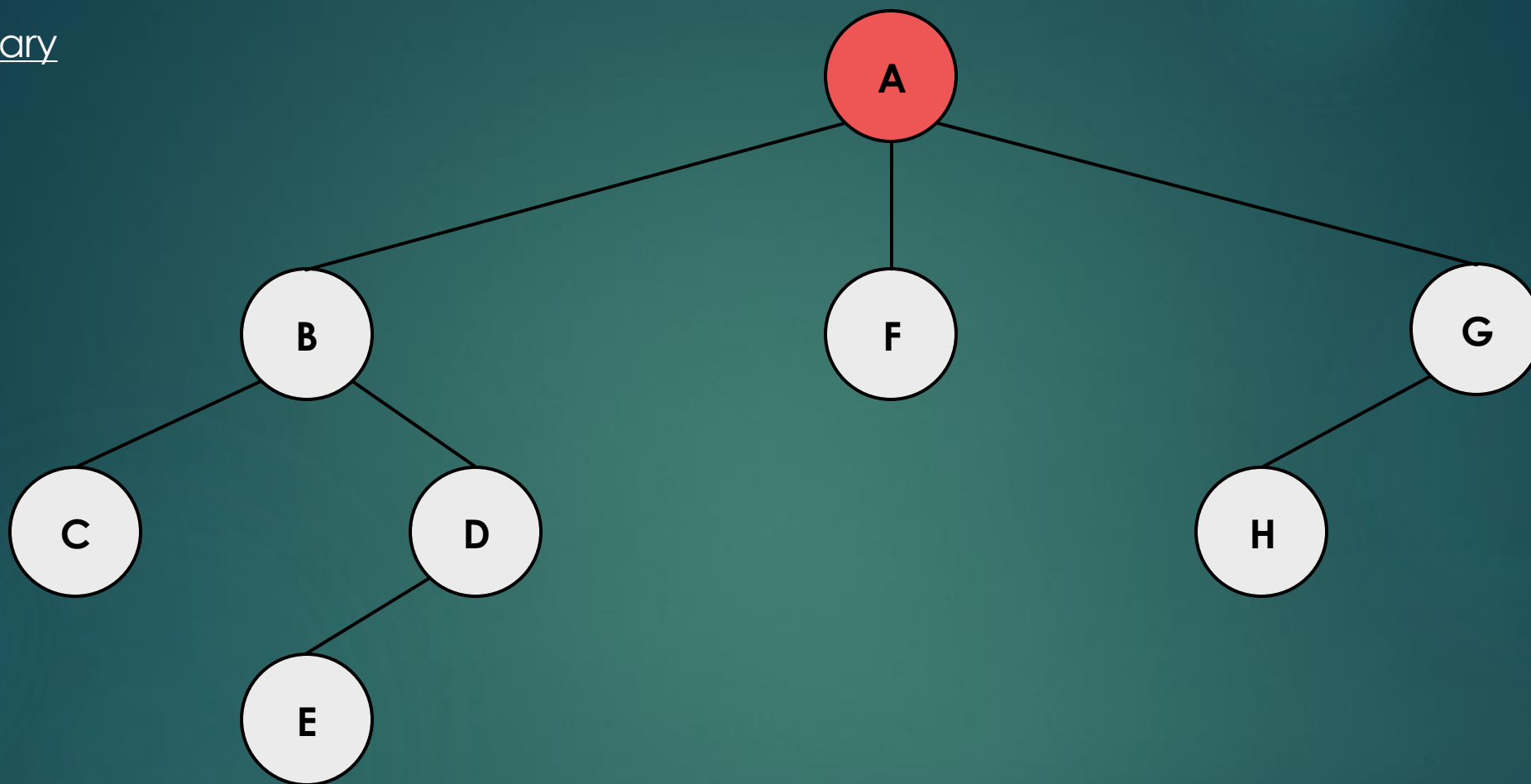


Queue: { } the queue is empty → **FINISHED !!!**

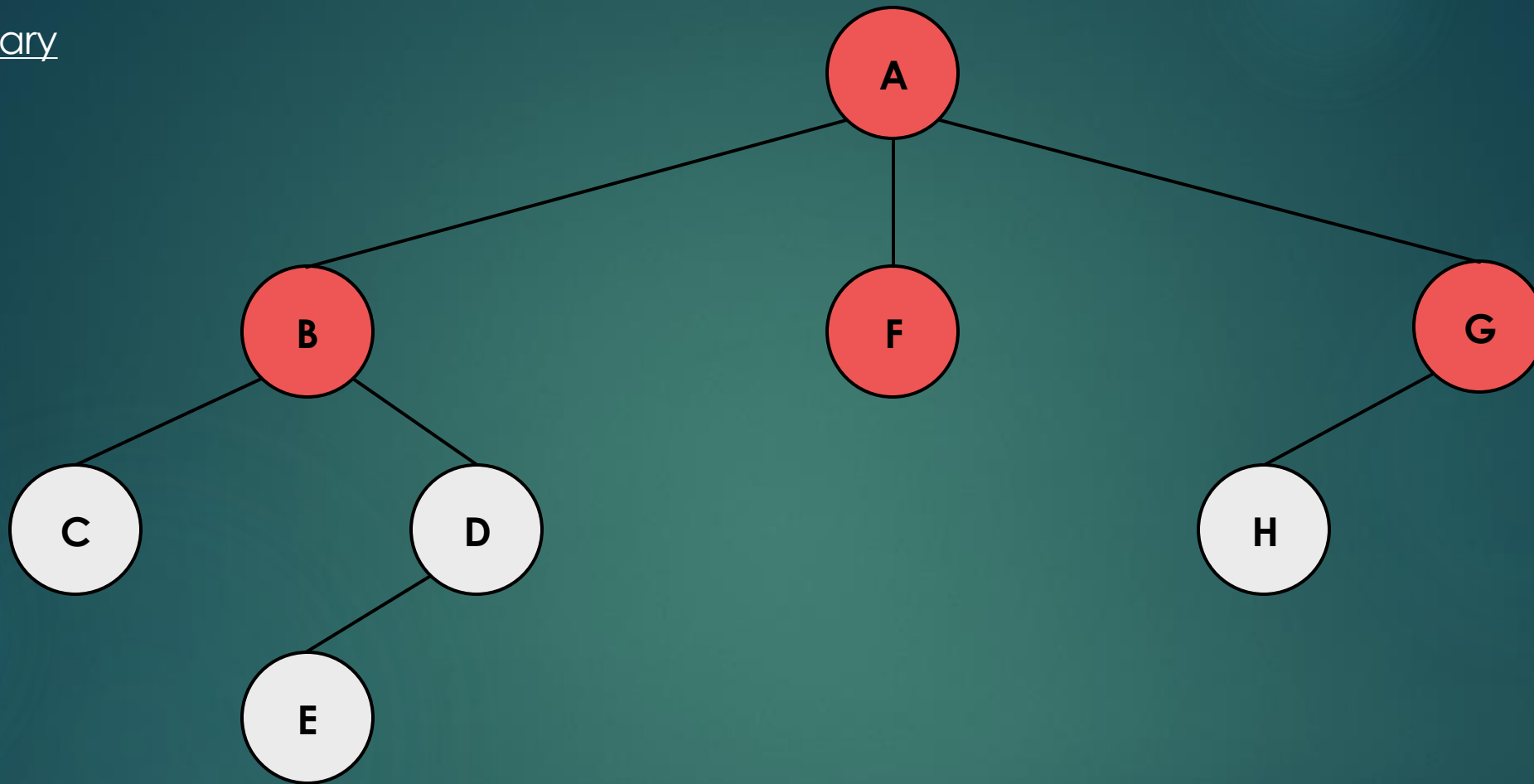
Summary



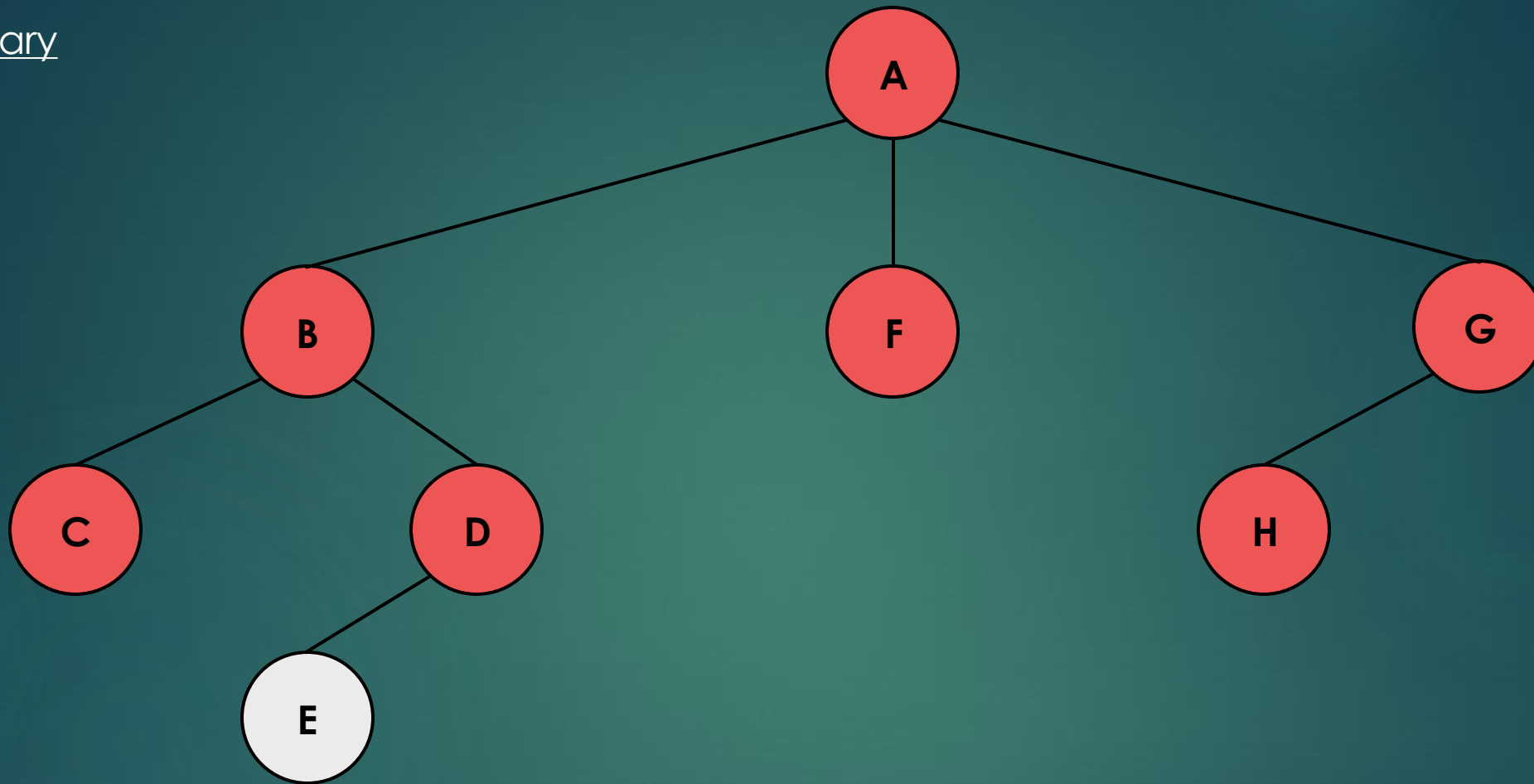
Summary



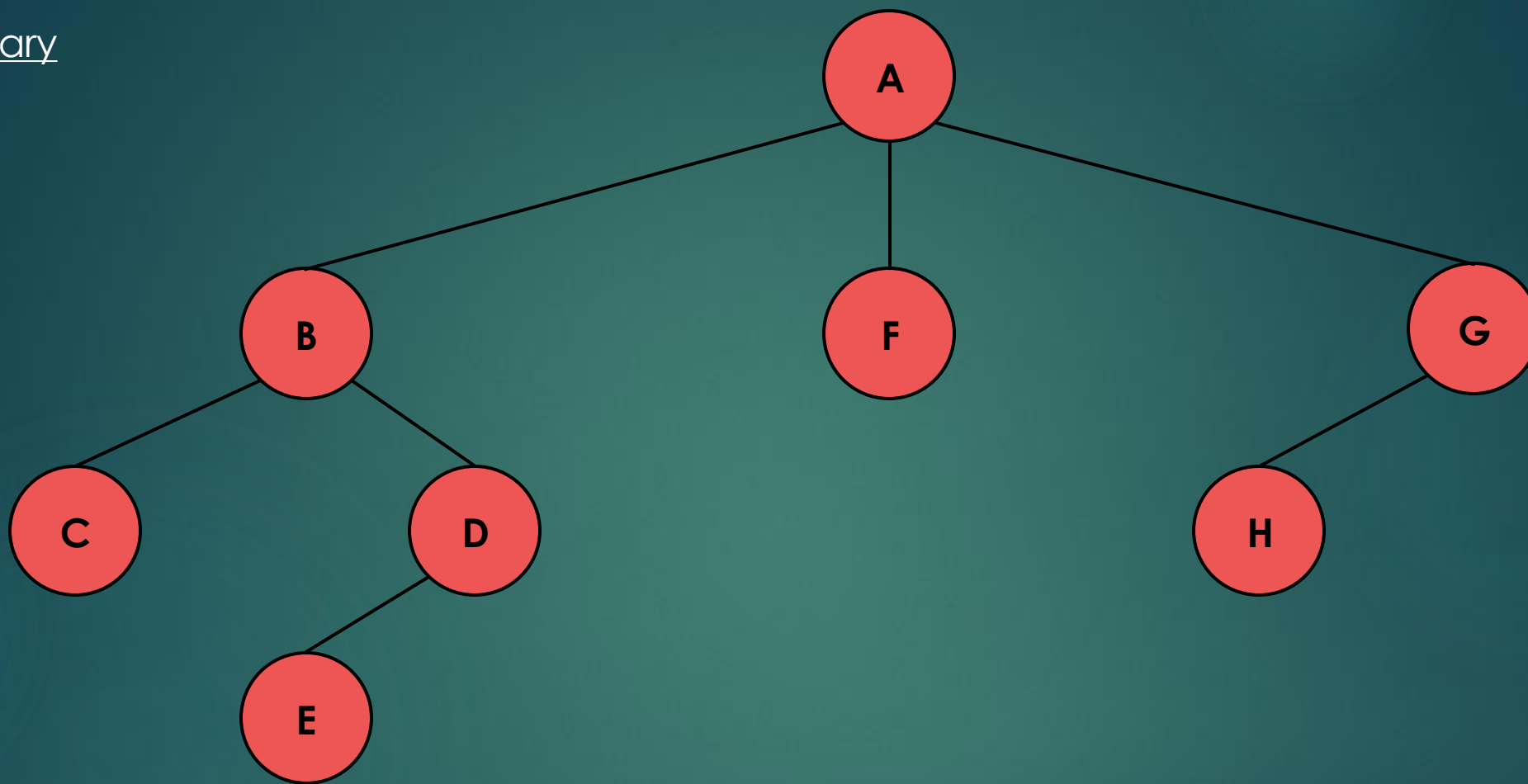
Summary



Summary



Summary



Applications

- ▶ In artificial intelligence / machine learning it can prove to be very important: robots can discover the surrounding more easily with BFS than DFS
- ▶ It is also very important in maximum flow: Edmonds-Karp algorithm uses BFS for finding augmenting paths
- ▶ Cheney's algorithm in garbage collection → it help to maintain active references on the heap memory
- ▶ It uses BFS to detect all the references on the heap
- ▶ Serialization / deserialization of a tree like structure (for example when order does matter) → it allows the tree to be reconstructed in an efficient manner !!!

DEPTH FIRST SEARCH

DFS

Depth-first search

- ▶ Depth-first search is a widely used graph traversal algorithm besides breadth-first search
- ▶ It was investigated as strategy for solving mazes by Trémaux in the 19th century
- ▶ It explores as far as possible along each branch before backtracking // BFS was a layer-by-layer algorithm
- ▶ Memory complexity: a bit better than that of BFS !!!

Depth-first search

dfs(vertex)

vertex set visited true
print vertex

for v in vertex neighbours
 if v is not visited
 dfs(v)

RECURSION

dfs(vertex)

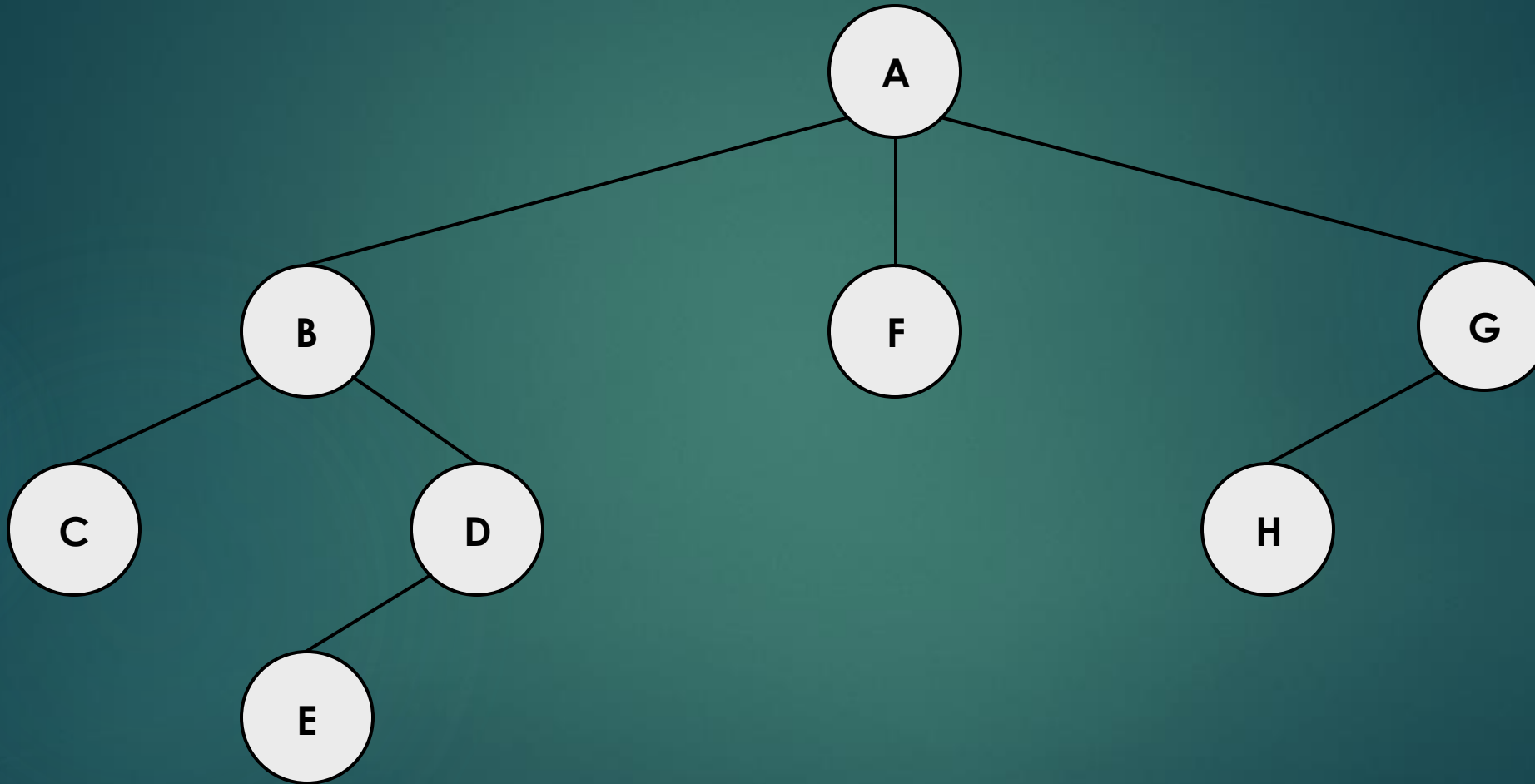
Stack stack
vertex set visited true
stack.push(vertex)

while stack not empty
 actual = stack.pop()

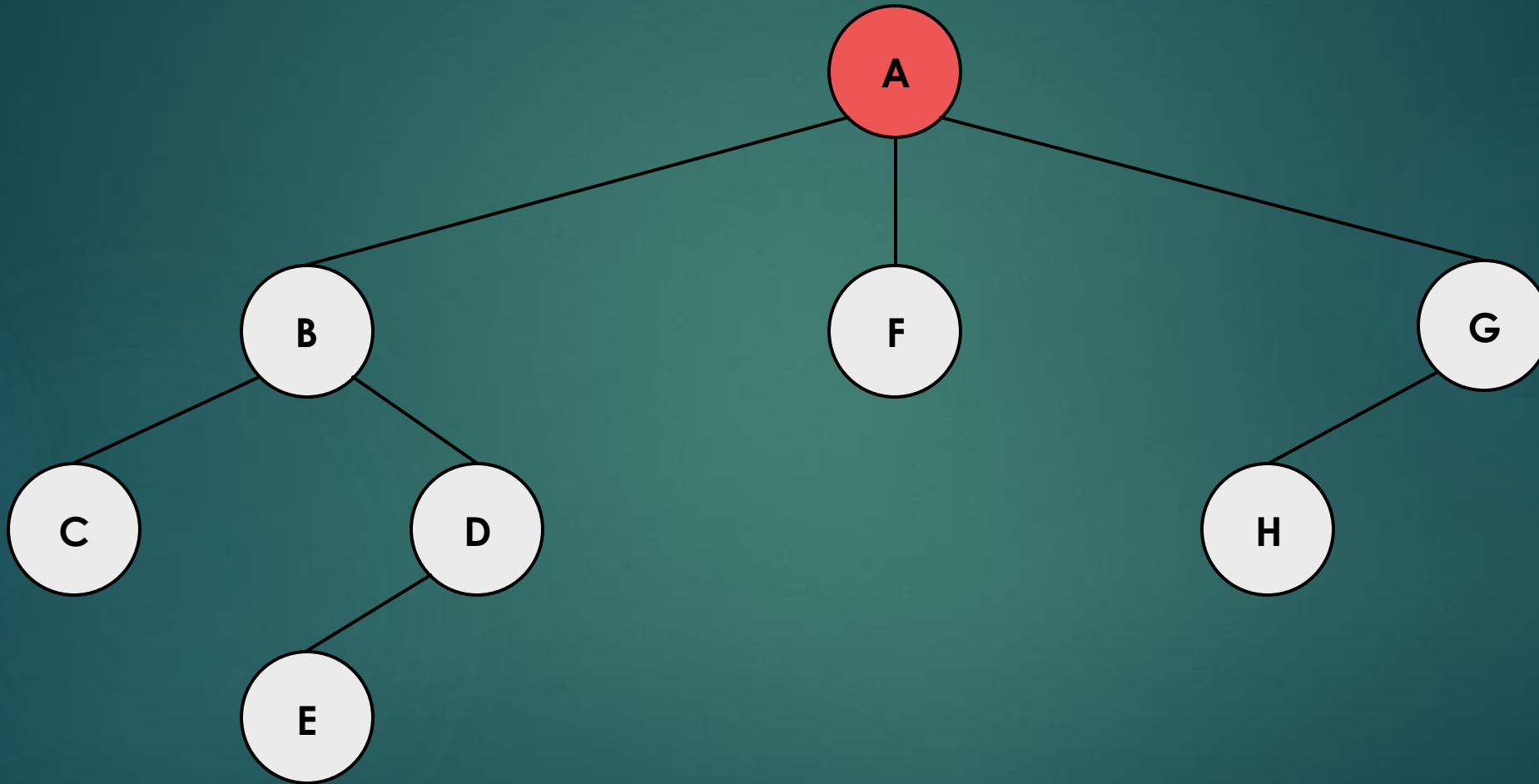
for v in actual neighbours
 if v is not visited
 v set visited true
 stack.push(v)

ITERATION

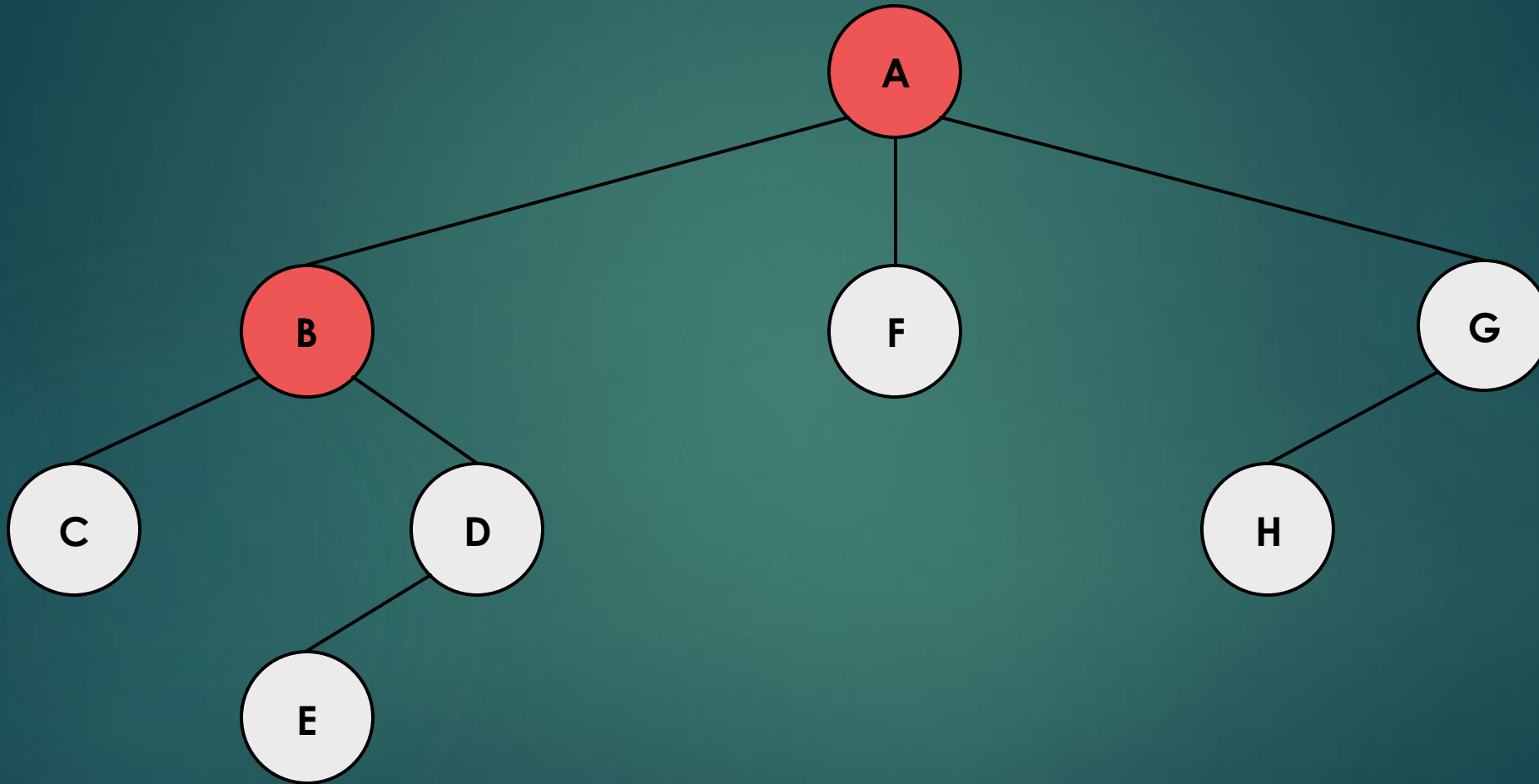
Recursively check every
unmarked vertices!



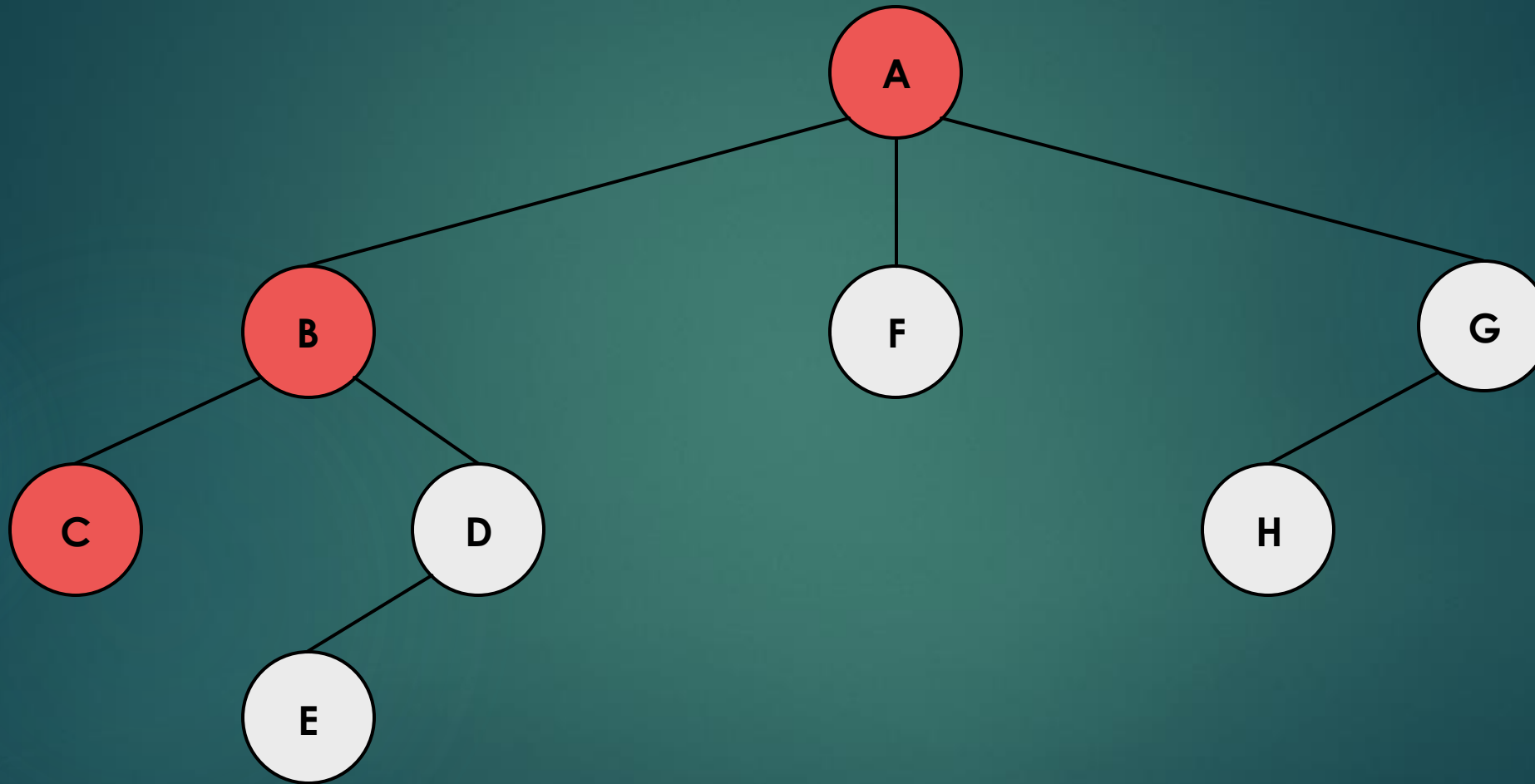
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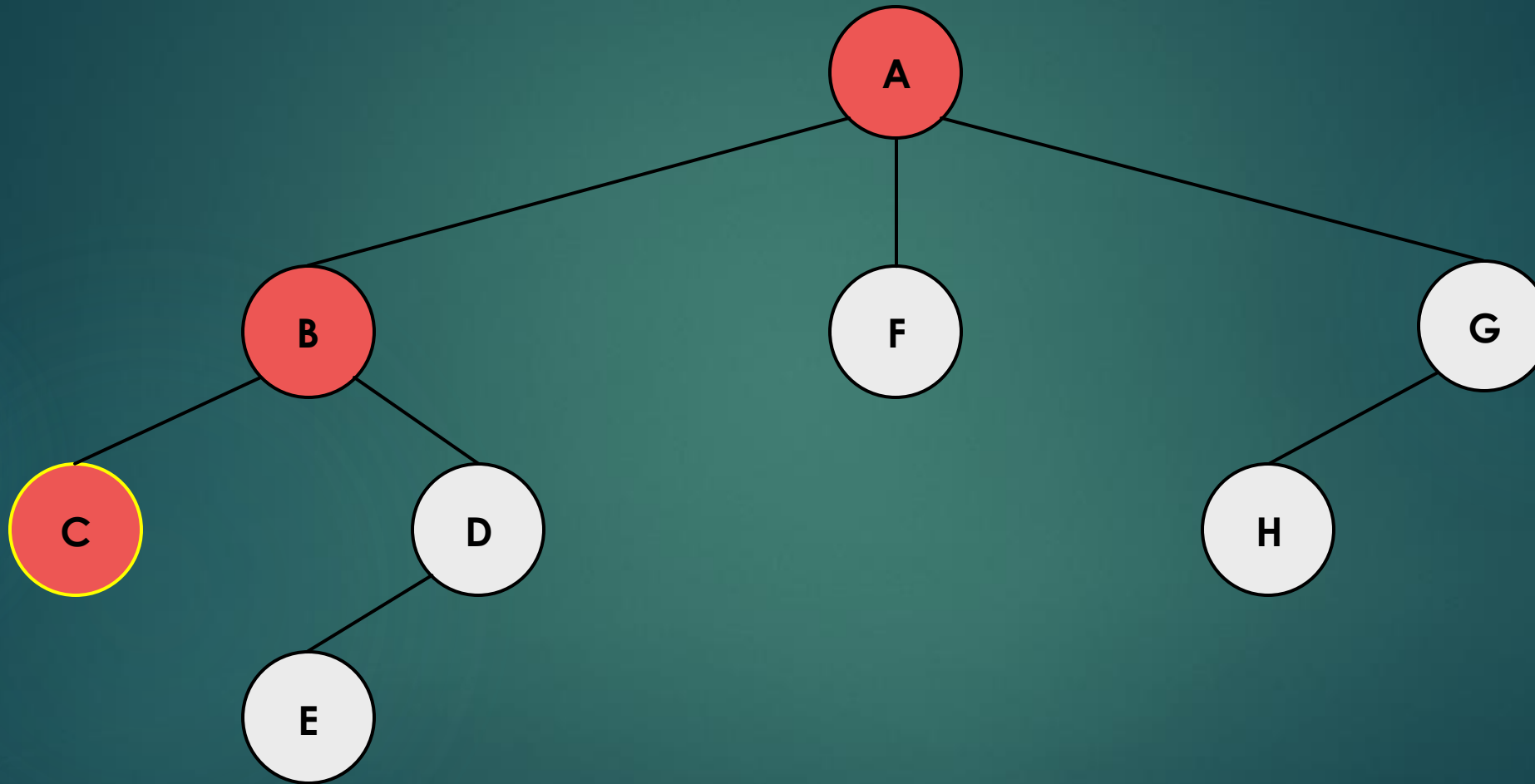
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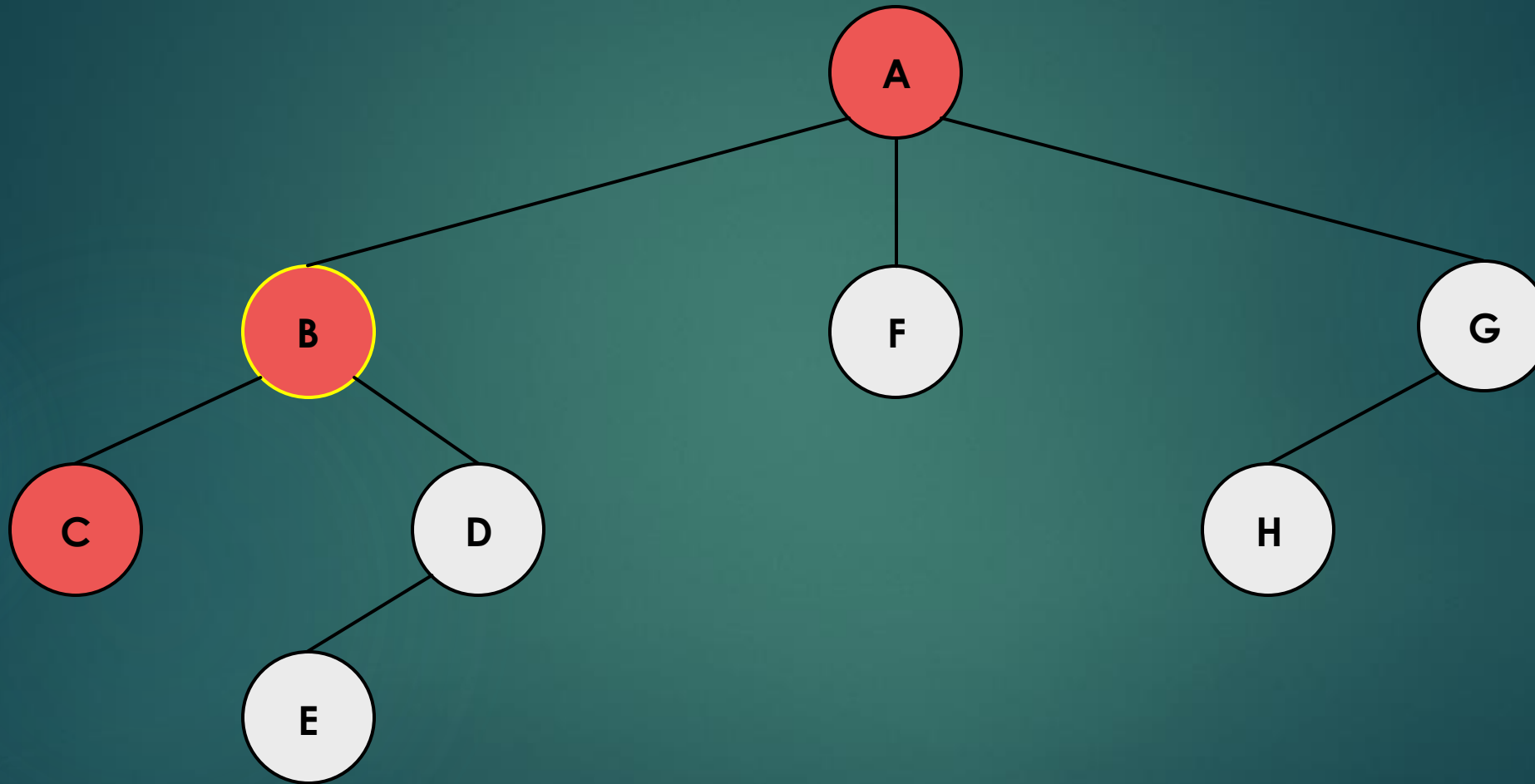
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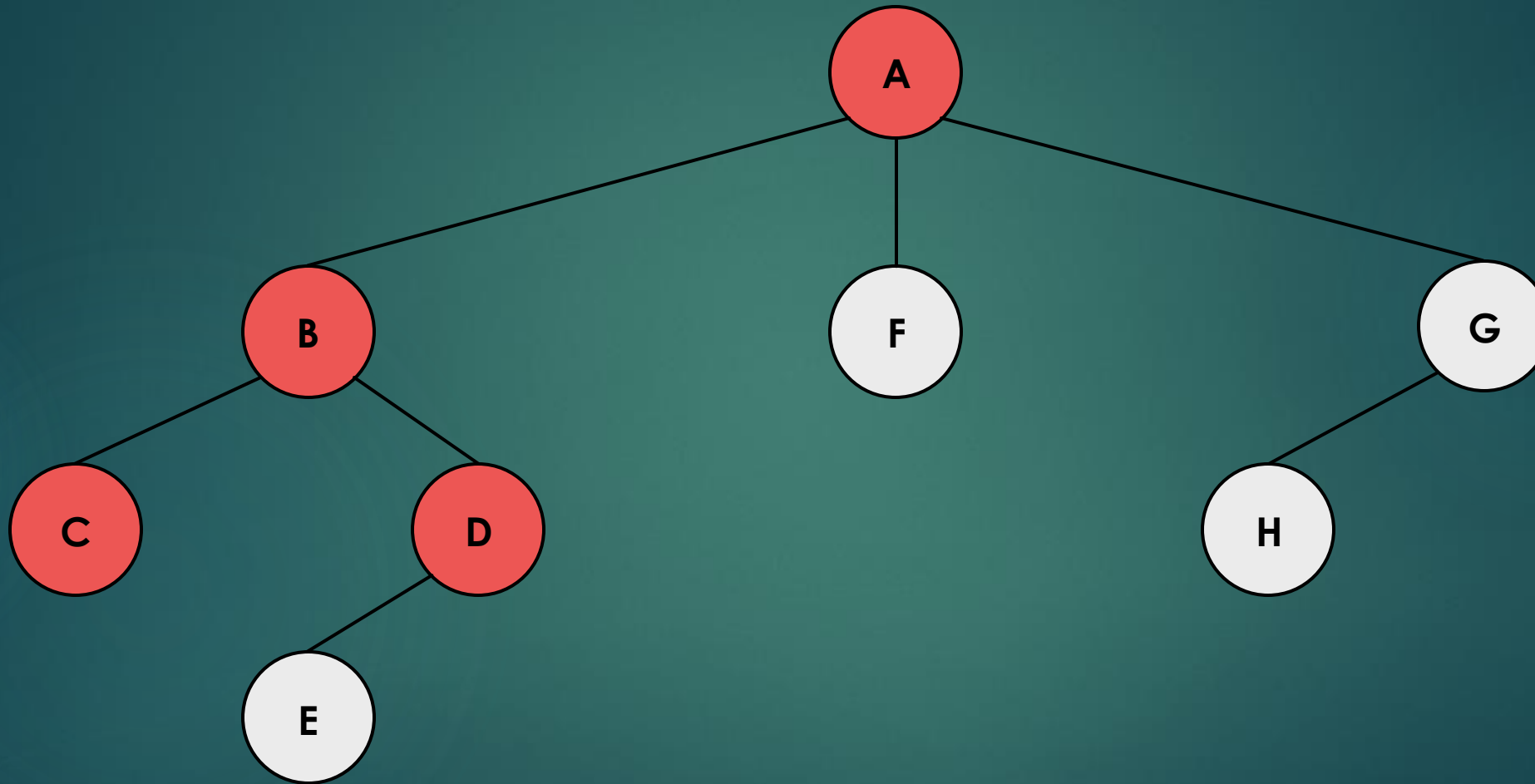
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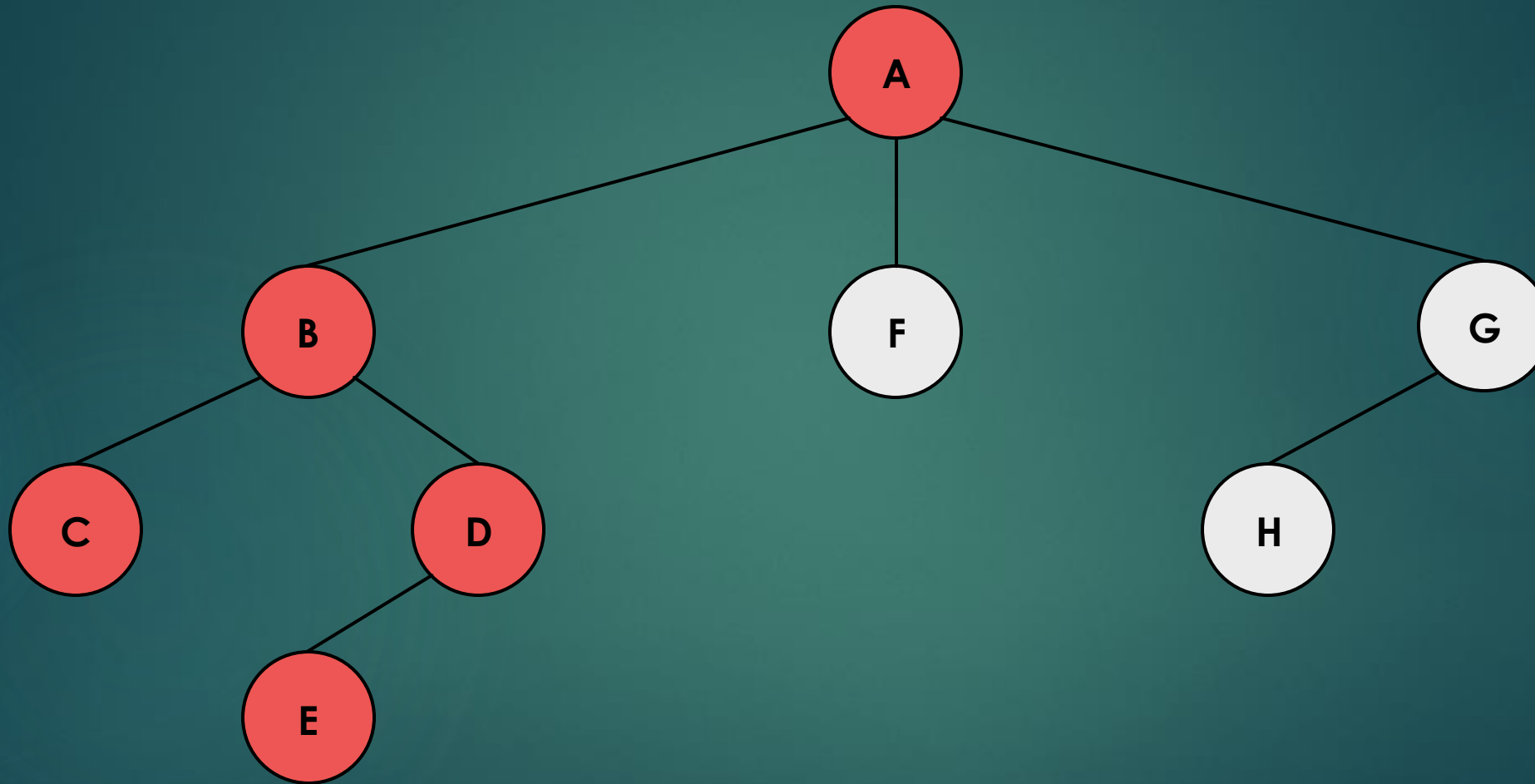
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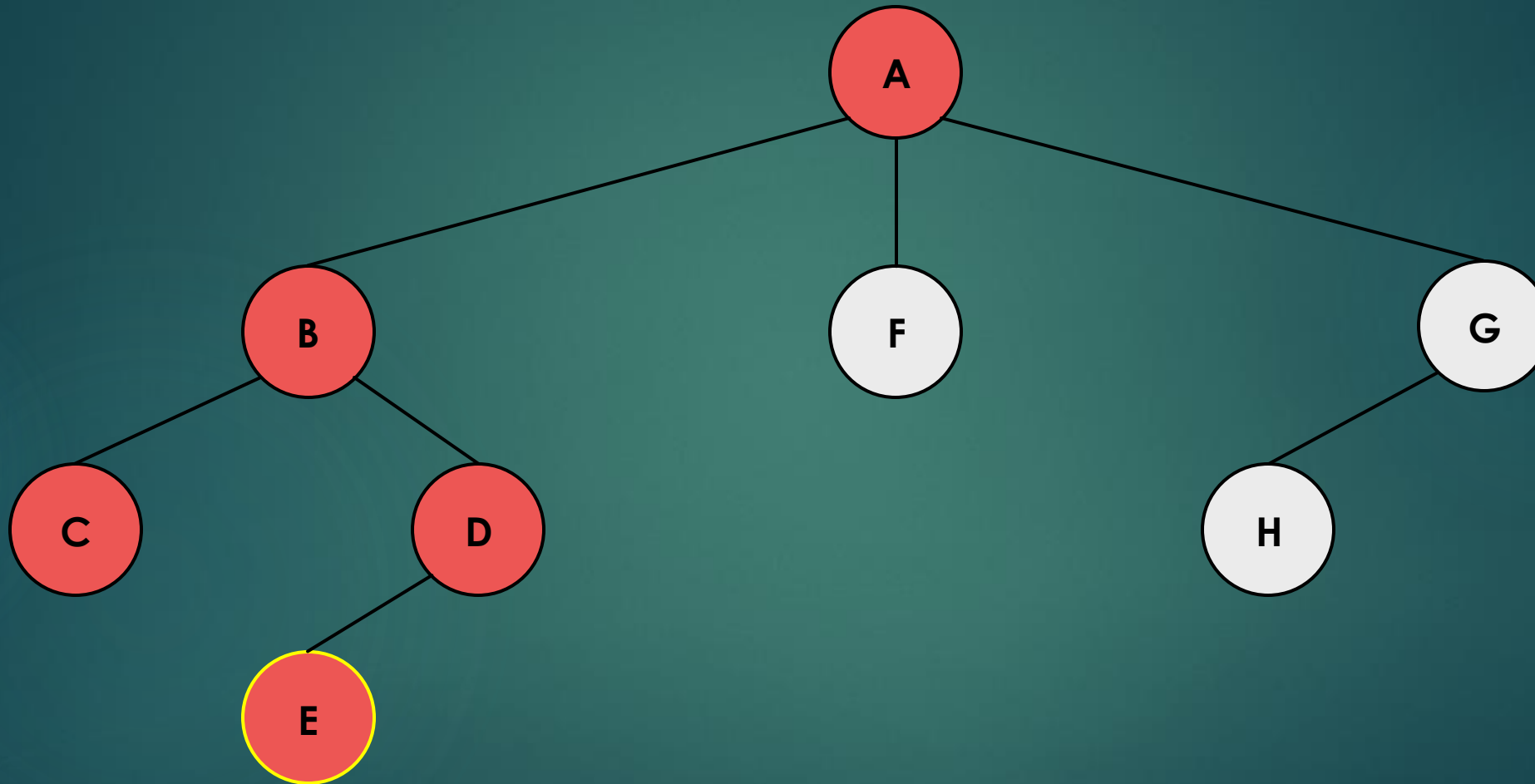
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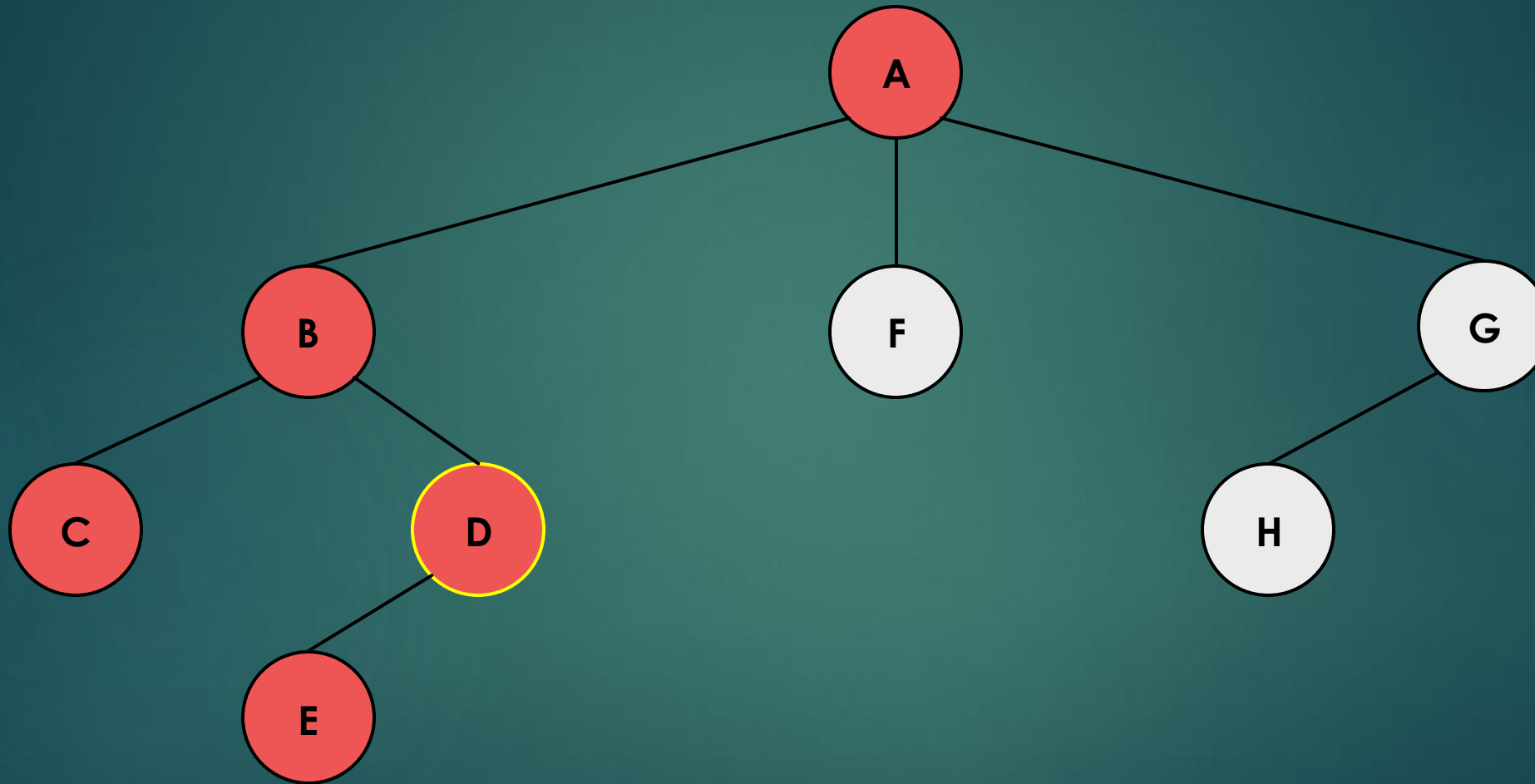
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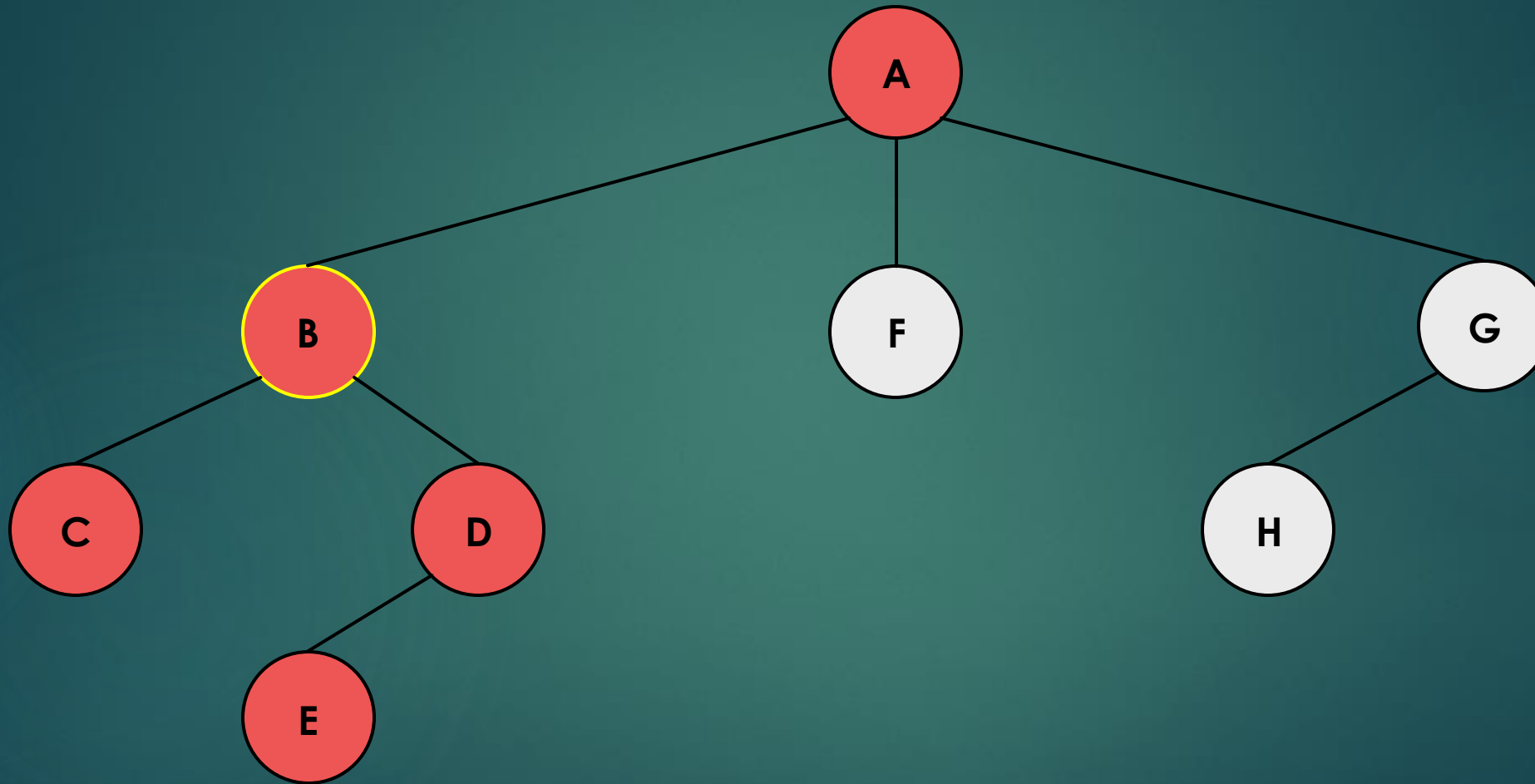
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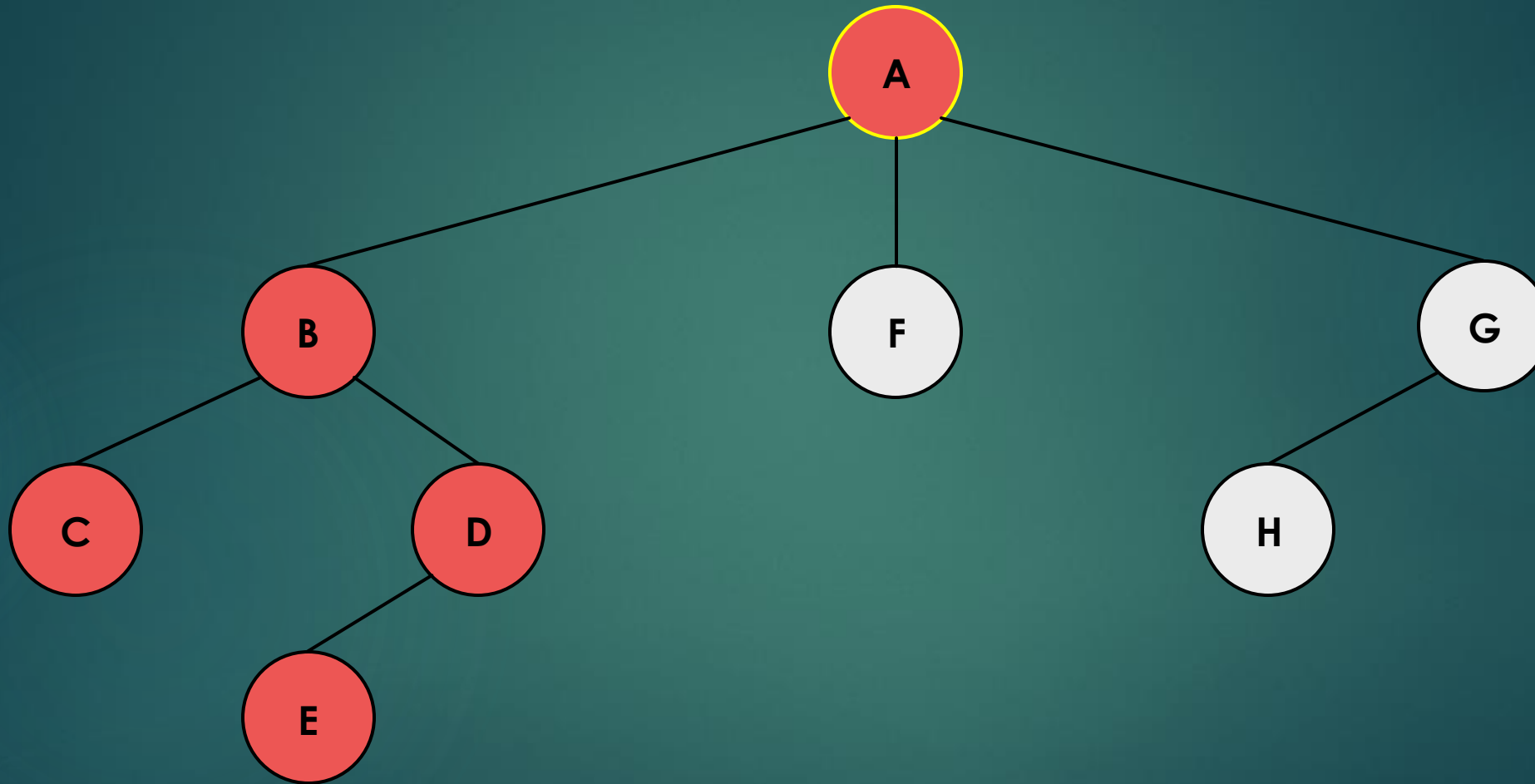
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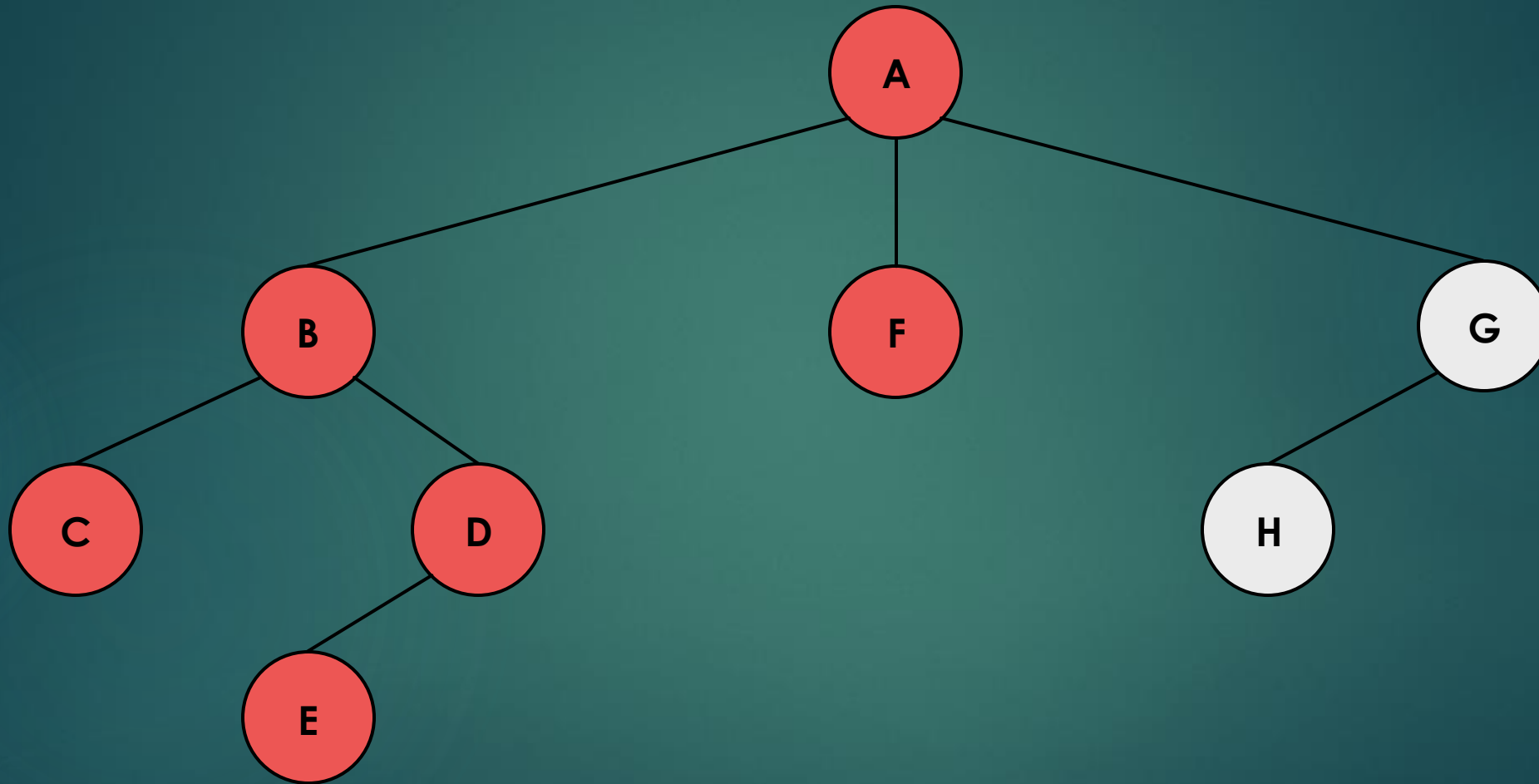
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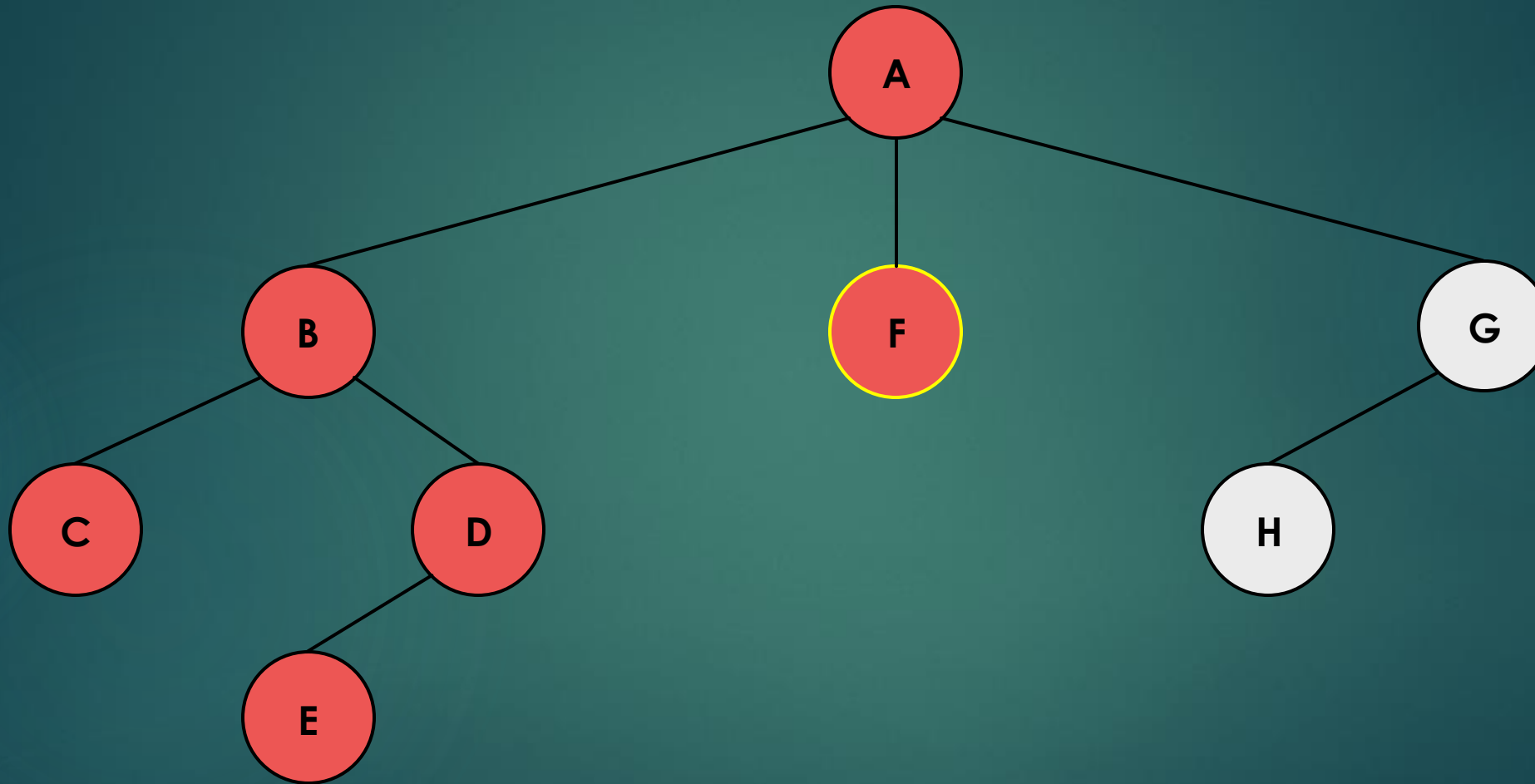
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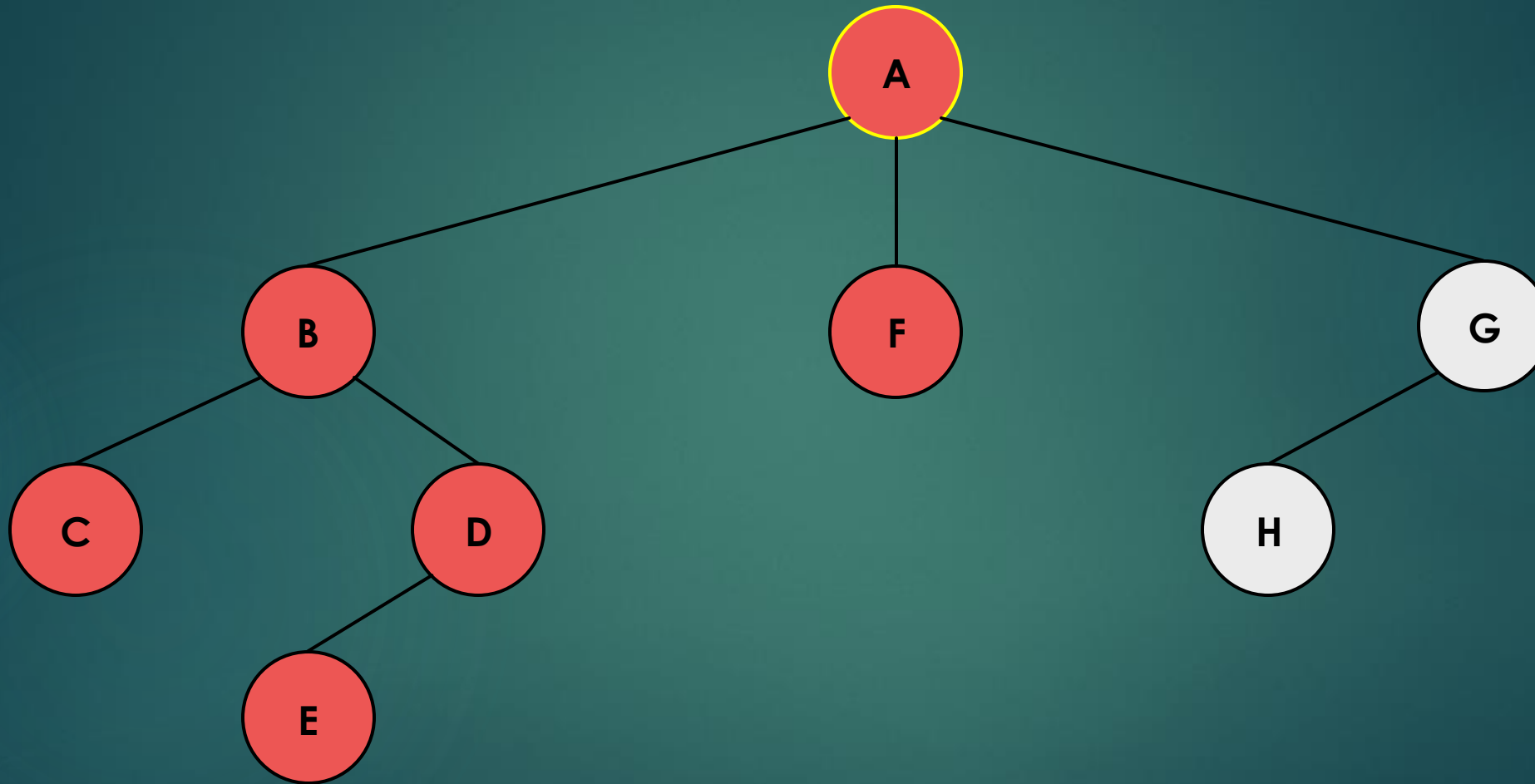
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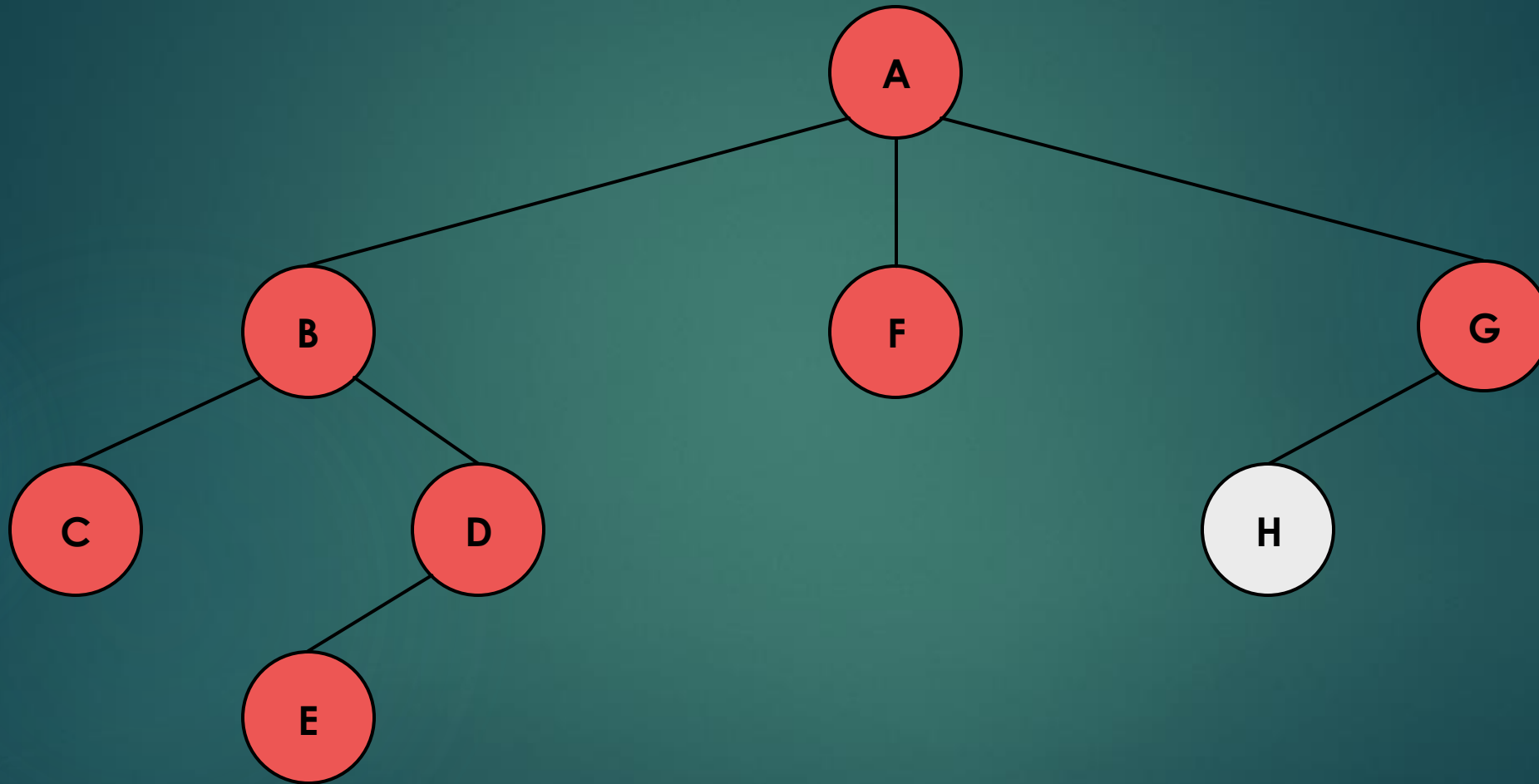
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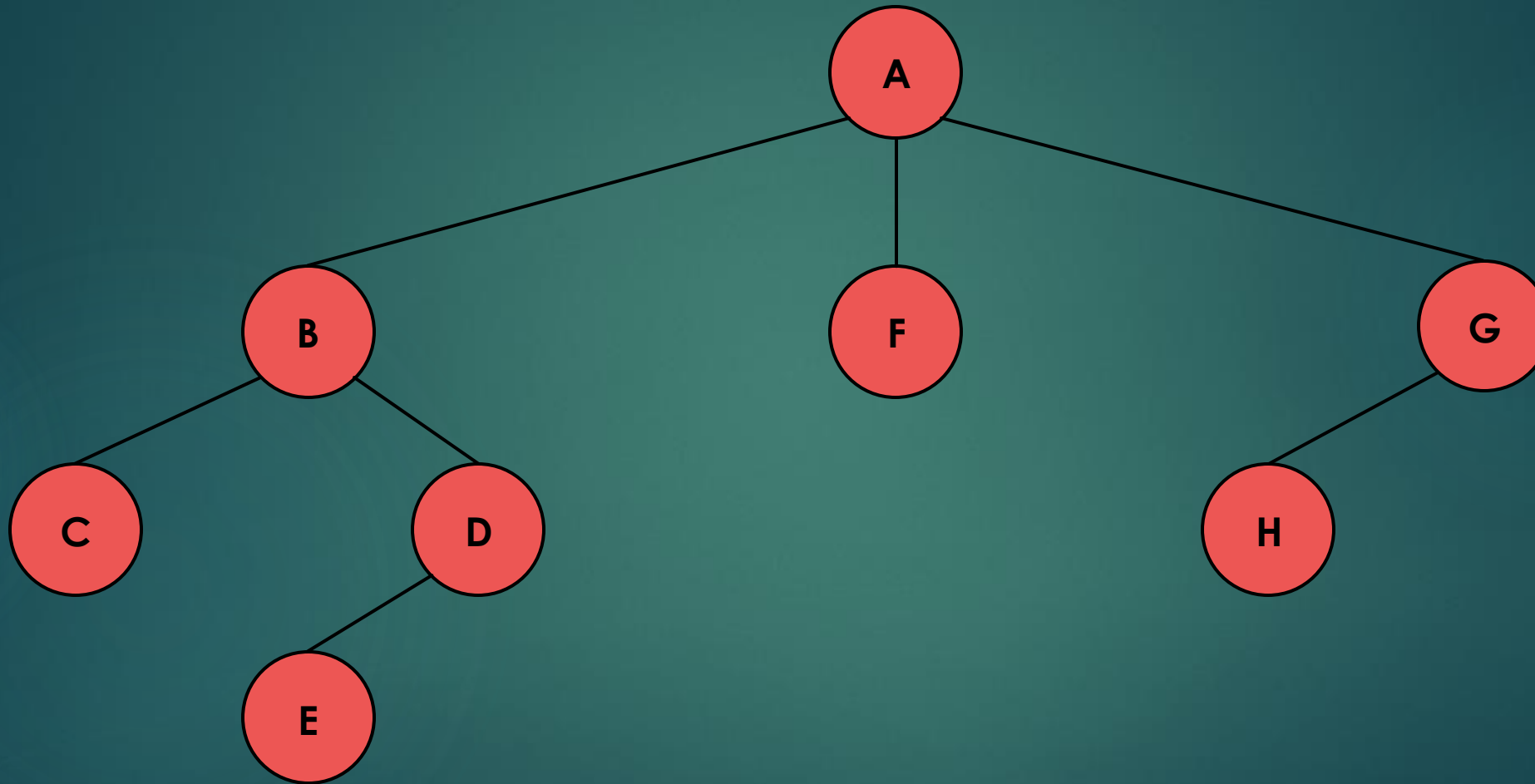
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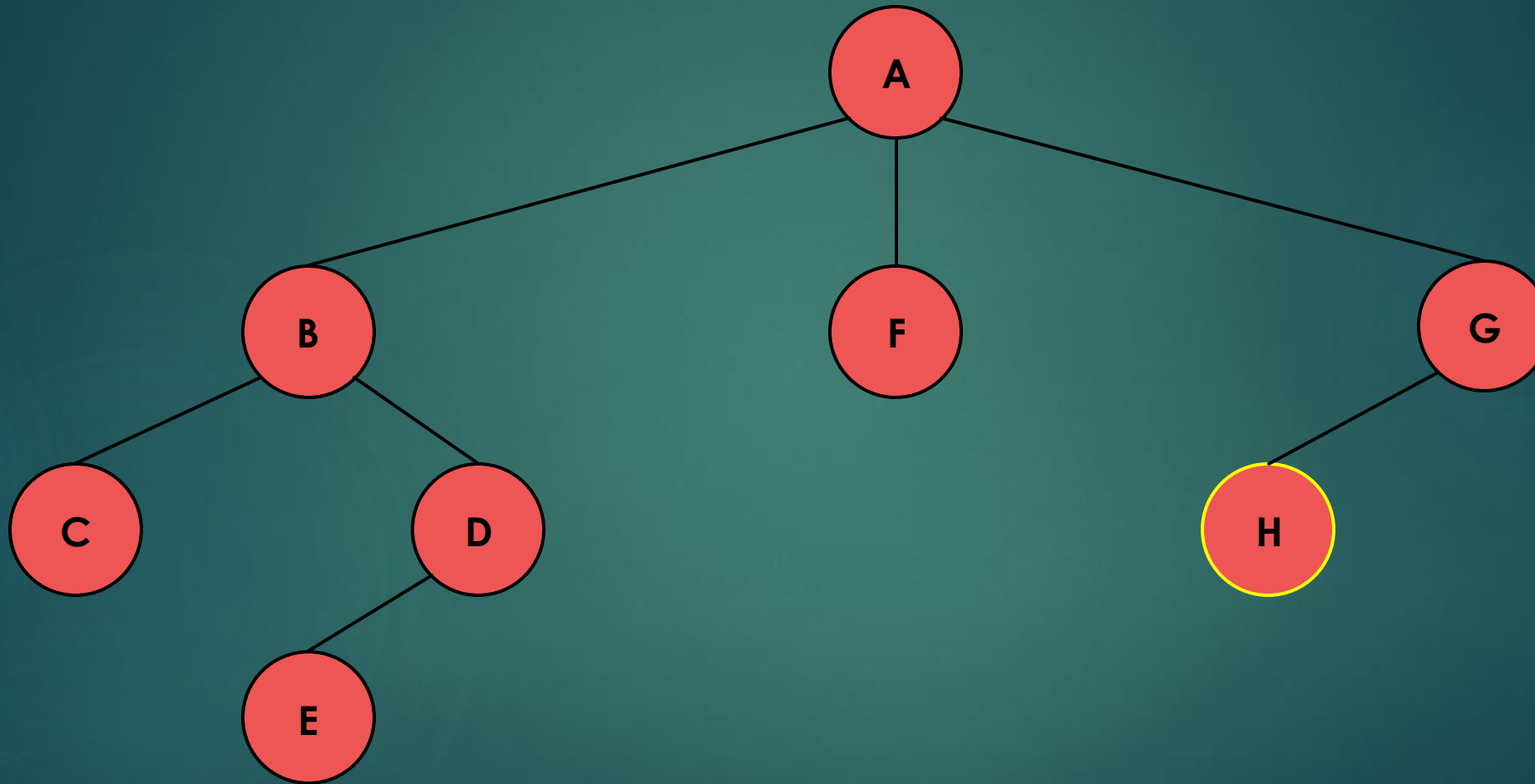
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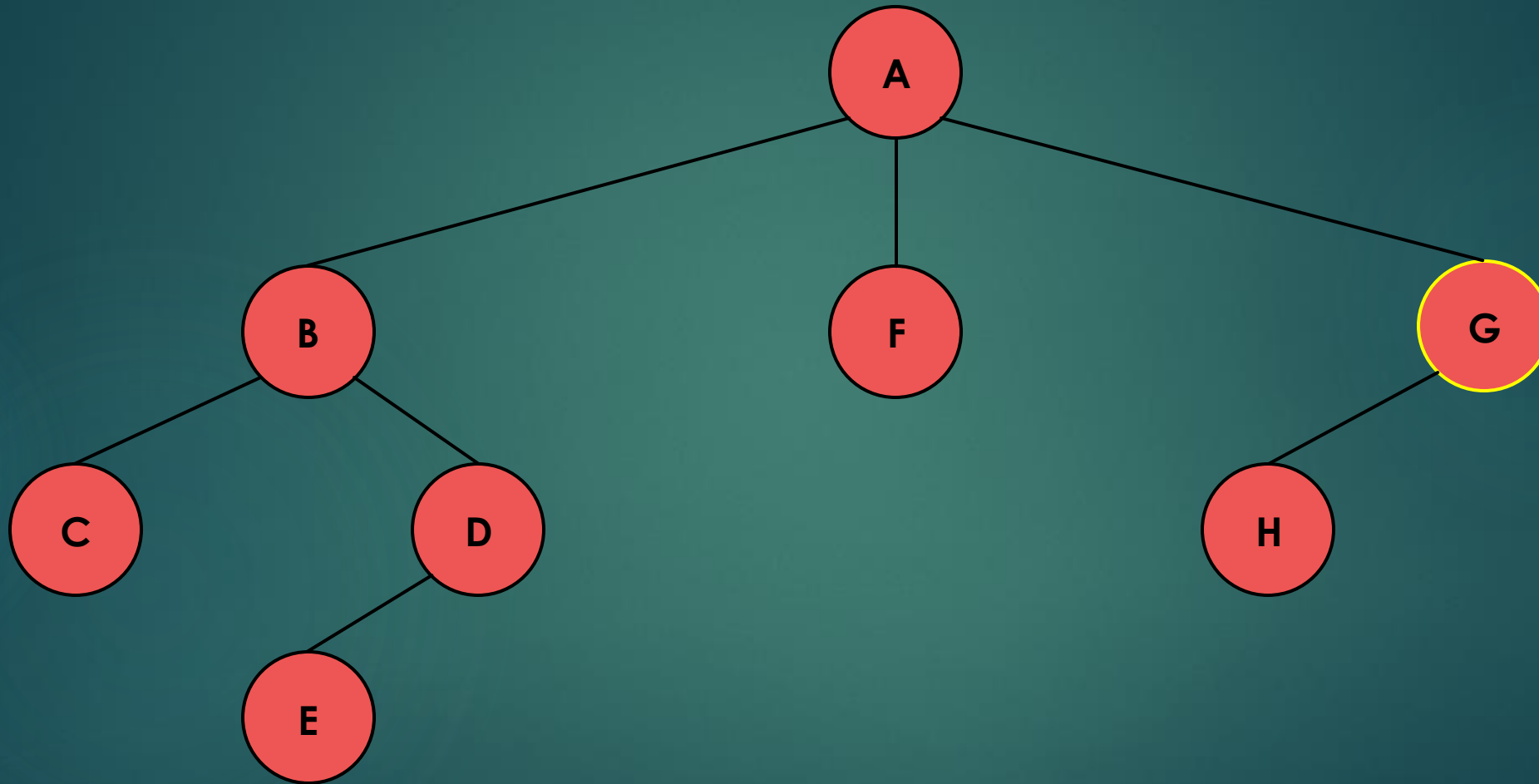
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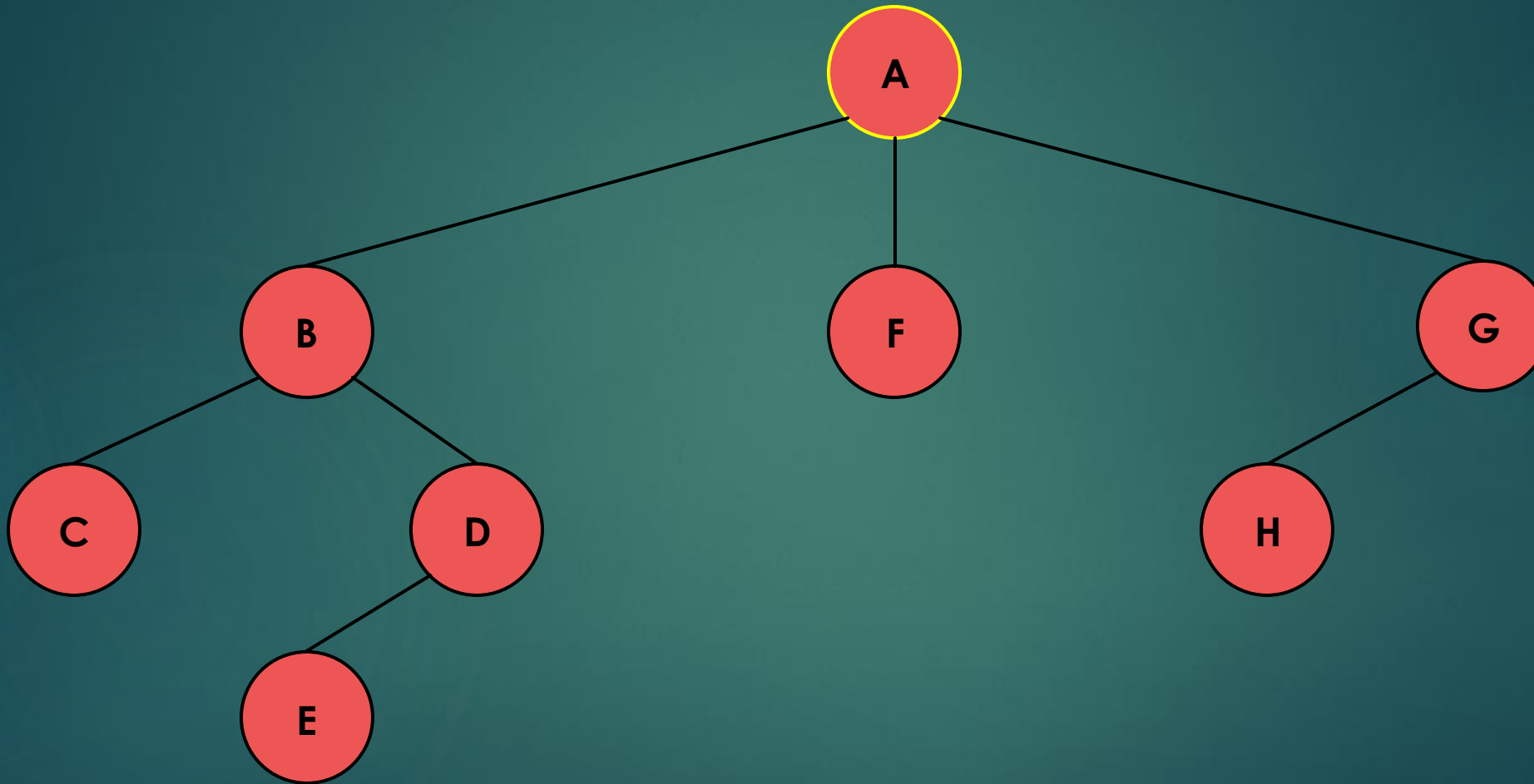
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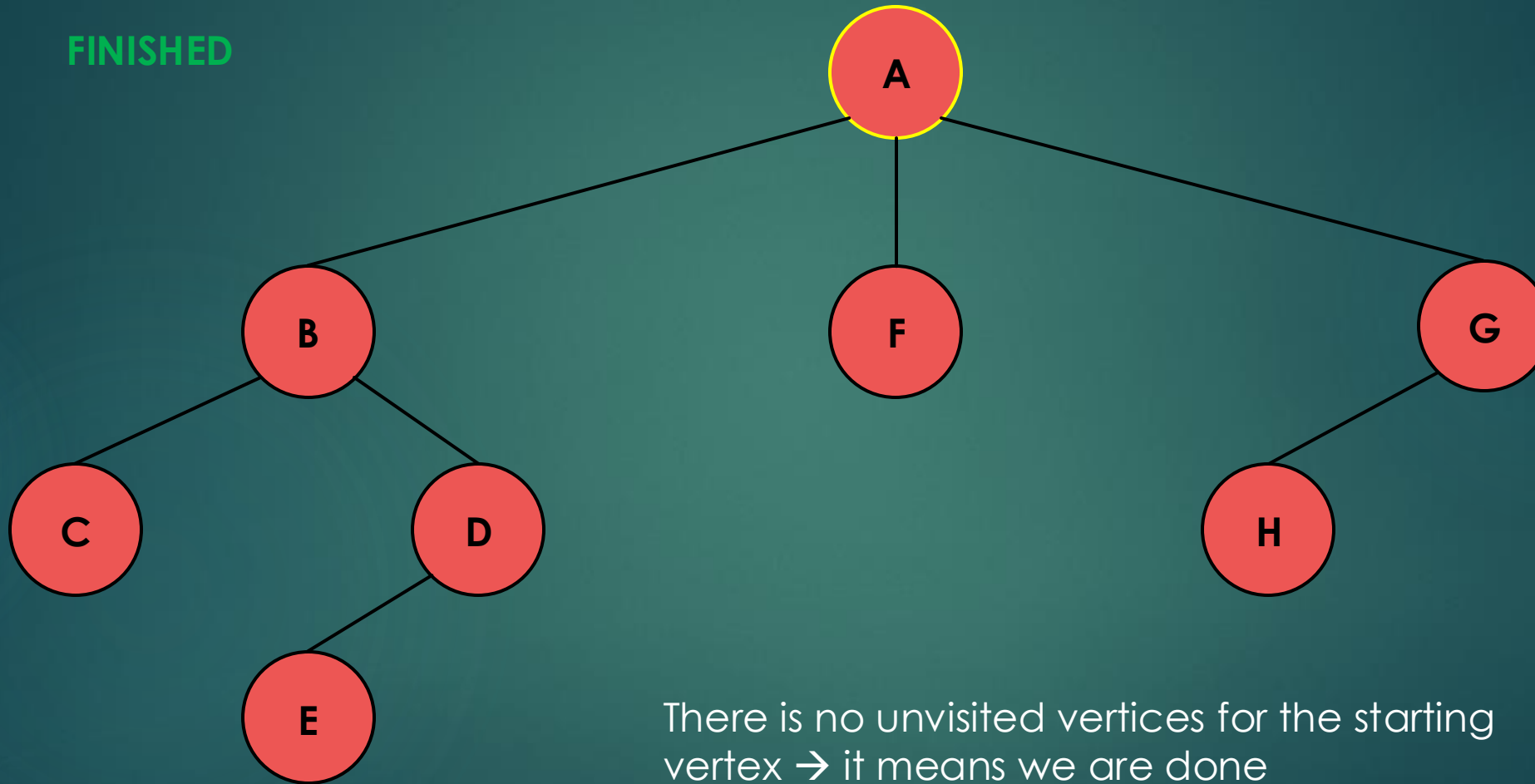


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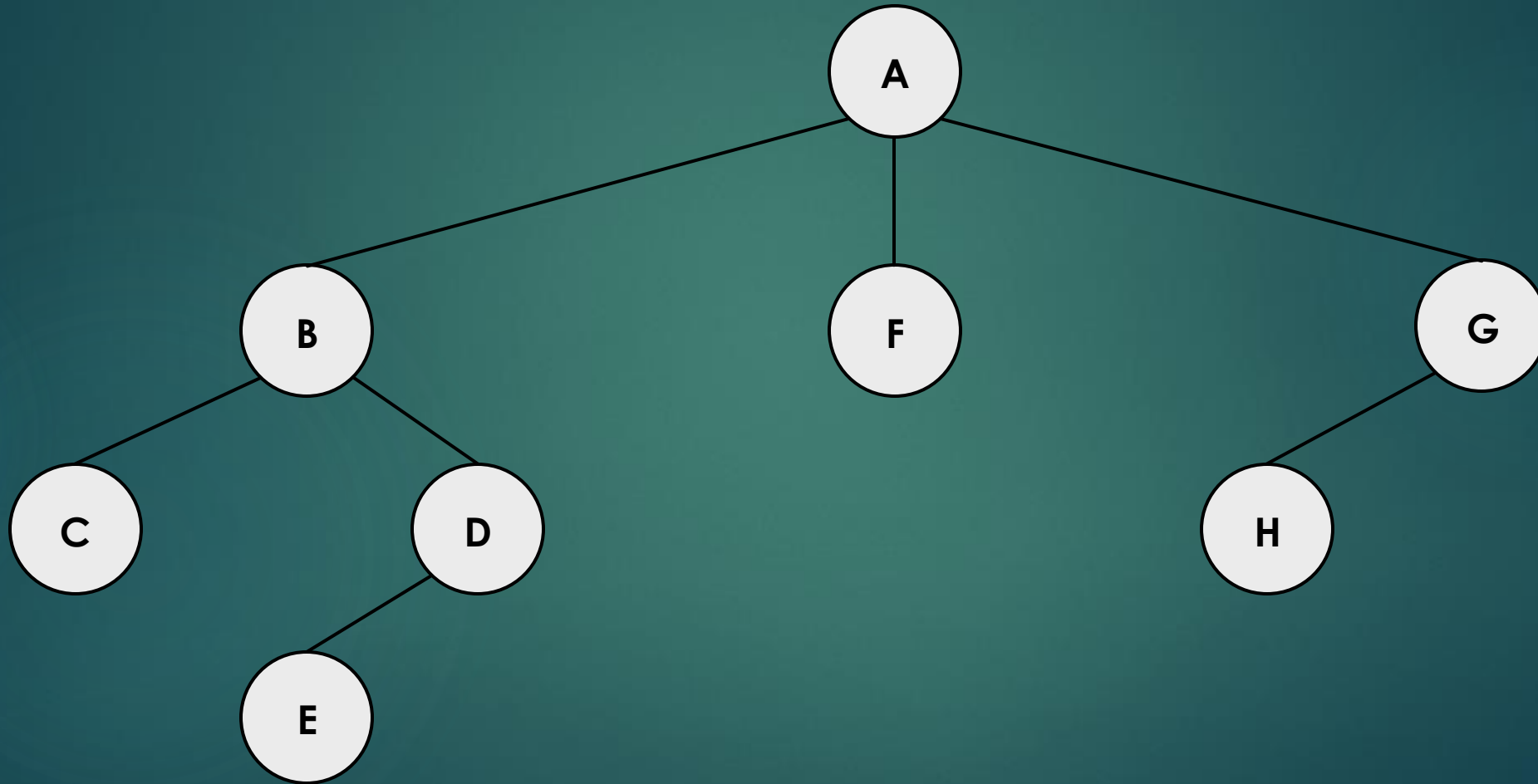
FINISHED



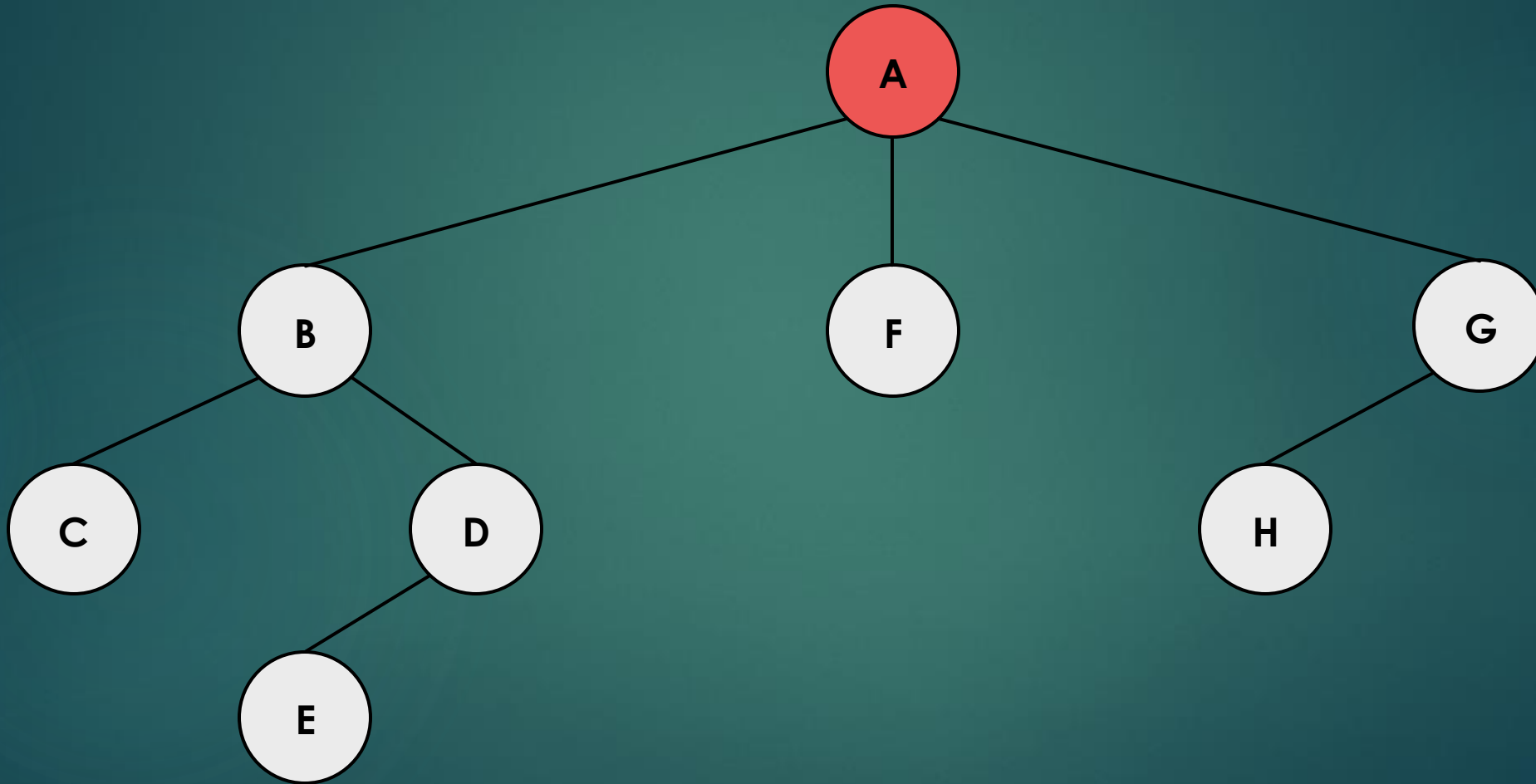
Applications

- ▶ Topological ordering
- ▶ Kosaraju algorithm for finding strongly connected components in a graph which can be proved to be very important in recommendation systems (youtube)
- ▶ Detecting cycles (checking whether a graph is a DAG or not)
- ▶ Generating mazes OR finding way out of a maze

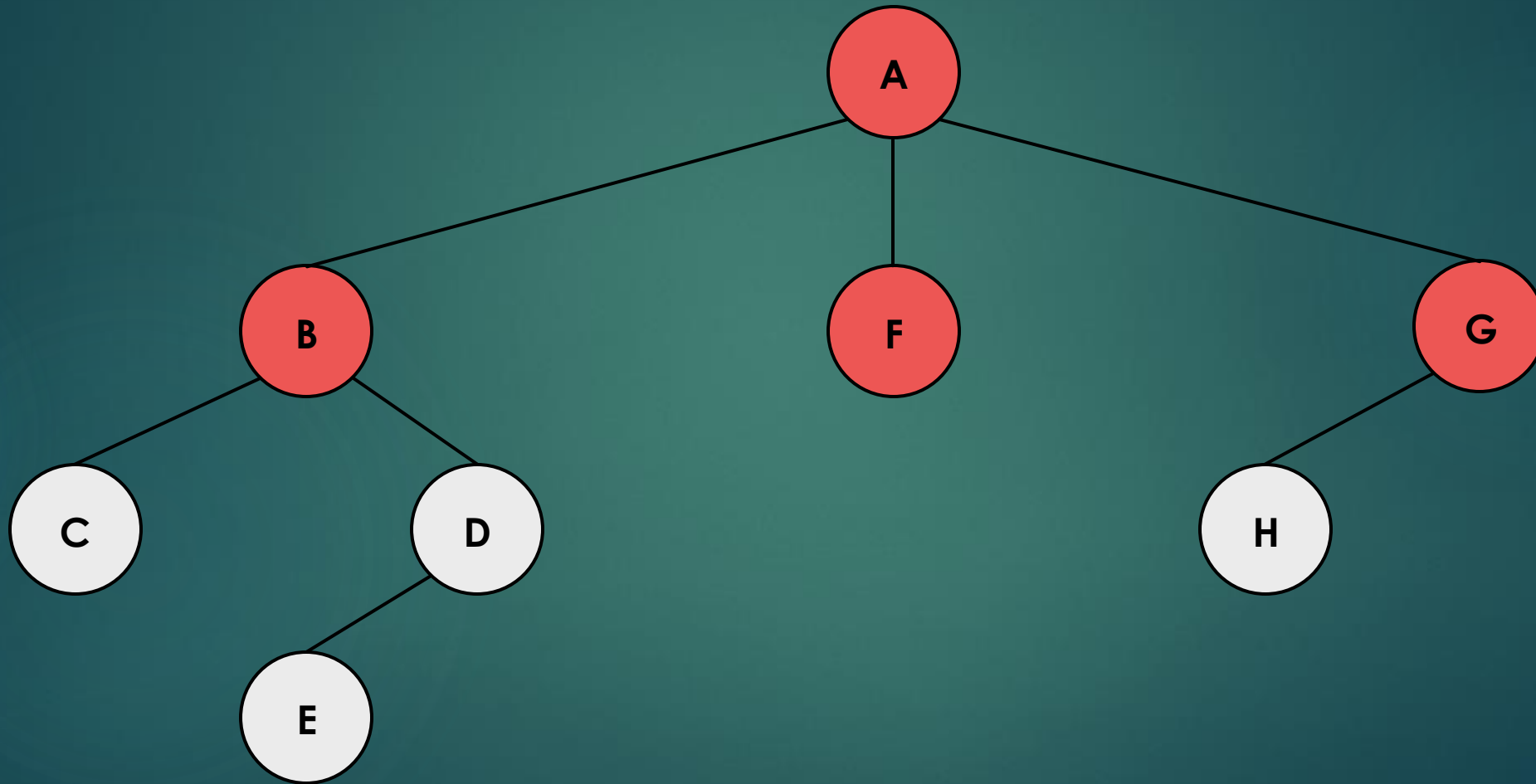
Revisiting breadth-first search



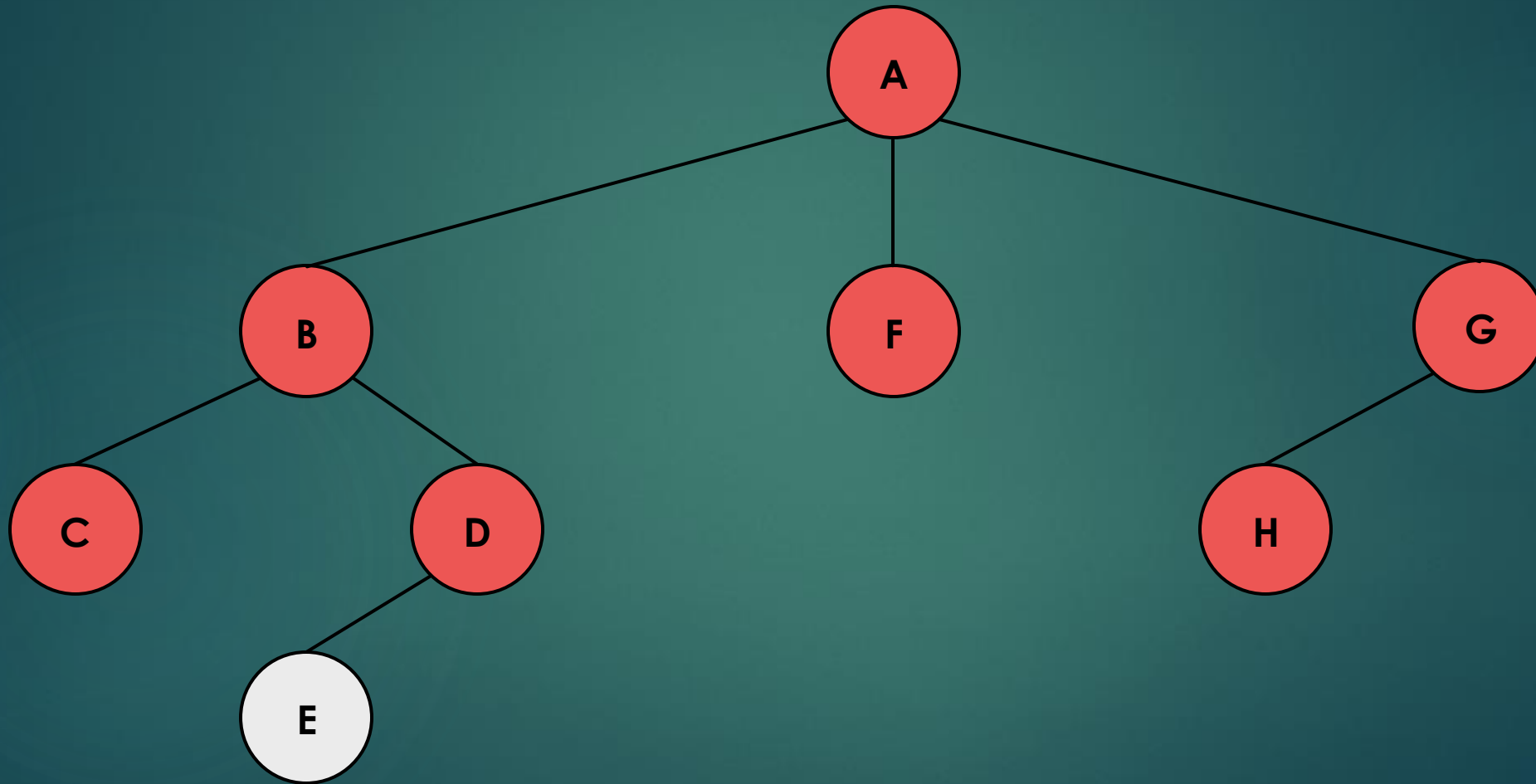
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